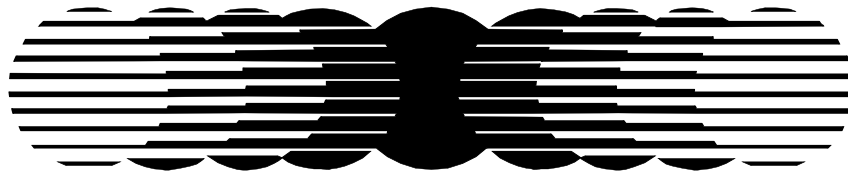


OPERATING MANUAL

2720 HARVESTER

Amity
TECHNOLOGY



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AMITY TECHNOLOGY LLC LIMITED WARRANTY TERMS AND CONDITIONS – UNITED STATES

EFFECTIVE FOR EQUIPMENT RETAILED AND DELIVERED AFTER JUNE 1, 2020

WHAT IS WARRANTED Amity Technology warrants its new equipment to be free of defects in material and workmanship at time of delivery to the first retail purchaser, renter, or lessee. Amity Technology warrants any new or unused part which is manufactured by Amity Technology for use in an Amity Technology machine, jointly referred to as "Products", whether such Product is purchased through an authorized Amity Technology dealer or directly from Amity Technology. Under this Warranty, Amity Technology will repair or replace, as it chooses in its sole discretion, any covered Product, or any component thereof, which Amity determines to be defective. These terms apply to all Amity Technology brands of new equipment originally marketed in the United States.

WARRANTY PERIOD

- 12 Months from the date of delivery to the first retail purchaser, renter or lessee.

EXCEPTIONS FROM THIS WARRANTY

- **Freight Charges** - This warranty does not cover freight charges.
- **Improvements, Changes, or Discontinuance** Amity Technology reserves the right to make changes and improvements in design or changes in specifications at any time to any product without incurring any obligations to owners of products previously sold.
- **Repairs and Maintenance Not Covered Under Warranty** - This warranty does not cover conditions resulting from misuse, natural calamities, use of non-Amity Technology parts, negligence, alteration, accident, use of unapproved attachments, usage which is contrary to the intended purposes, or conditions caused by failure to perform required maintenance. Replacement of Wear or Maintenance items (unless defective) such as but not limited to, filters, hoses, belts, lubricants, light bulbs, wheel alignment, tightening of nuts, belts, bolts, and fittings, service tune-up, computer parameter adjustments and general adjustments which may from time to time be required are not covered.
- **Rubber Tire Warranty** - Rubber tires are warranted directly by the respective manufacturer only and not by Amity Technology.

OWNER'S OBLIGATION

It is the responsibility of the Owner to transport the equipment or parts to the service shop of an authorized Amity Technology Dealer or alternatively to reimburse the Dealer for any travel or transportation expense involved in fulfilling this warranty. This Warranty does NOT cover rental of replacement equipment during the repair period, damage to products which have been declared a total loss and subsequently salvaged, overtime labor charges, freight charges for replacement parts, or special handling requirements (such as, but not limited to, the use of cranes).

EXCLUSIVE EFFECT OF WARRANTY AND LIMITATION OF LIABILITY

THIS WARRANTY IS IN LIEU OF ALL WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PURPOSE OR OTHER REPRESENTATIONS, WARRANTIES OR CONDITIONS, EXPRESSED OR IMPLIED. The remedies of the Owner set forth herein are exclusive. The Company neither assumes nor authorizes any person to assume for it any other obligation or liability in connection with the sale of covered machines. Correction of defects, in the manner and for applicable period of time provided above, shall constitute fulfillment of all responsibilities of Amity Technology to the Owner, and Amity Technology shall not be liable for negligence under contract or in any manner with respect to such machines. IN NO EVENT SHALL THE OWNER BE ENTITLED TO RECOVER FOR INCIDENTAL, SPECIAL OR CONSEQUENTIAL DAMAGES SUCH AS BUT NOT LIMITED TO, LOSS OF CROPS, LOSS OF PROFITS OR REVENUE, OTHER COMMERCIAL LOSSES, INCONVENIENCE OR COST OF RENTAL OR REPLACEMENT EQUIPMENT.

Some States or Provinces do not permit limitations or exclusions of implied warranties or incidental or consequential damages, so the limitations or exclusions in this warranty may not apply.

Additional Warranty Information

New Equipment Warranty - Equipment is eligible for warranty service only if it qualifies under the provisions of the New Equipment Warranty. The selling dealer will deliver this Warranty to the original retail purchaser at the time of sale, and the dealer will register the sale and Warranty with Amity Technology LLC.

Subsequent Owners - This Warranty covers the first retail purchaser and all subsequent owners of the equipment during the specified warranty period. Should the Amity Technology Dealer sell this equipment to a subsequent owner, the Dealer must deliver the warranty document to the subsequent owner so the subsequent owner can register ownership with Amity Technology and obtain the remaining warranty benefits, if available, with no intermission in the Warranty Period. Subsequent Owner Procedure will apply. It is the responsibility of the subsequent owner to transport the equipment to the service shop of an authorized Amity Technology Dealer or alternatively to reimburse the Dealer for any travel or transportation expense involved in fulfilling this warranty. This Warranty does NOT cover charges for rental or replacement equipment during the repair period, products which have been declared a total loss and subsequently salvaged, overtime labor charges, freight charges for replacement parts, or units sold at auction.

Warranty Service - To be covered by Warranty, service must be performed by an authorized Amity Technology Dealer. It is recommended that you obtain warranty service from the Dealer who sold you the equipment because of that Dealer's continued interest in you as a valued customer. In the event this is not possible, warranty service may be performed by any other authorized Amity Technology Dealers in the United States or Canada. It is the responsibility of the Owner to transport the equipment to the service shop of an authorized Amity Technology Dealer or alternatively to reimburse the Dealer for any travel or transportation expense involved in fulfilling this warranty.

Maintenance Service - The Owner's Manual furnished to you with the equipment at the time of delivery contains important maintenance and service information. You must read the manual carefully and follow all the maintenance and service recommendations. Doing so will result in greater satisfaction with your equipment and help avoid service and warranty problems. Please remember that failures due to improper maintenance of your equipment are not covered by warranty.

Maintenance Inspections - To insure the continued best performance from your agricultural equipment, we recommend that you arrange to make your equipment available to your selling Dealer for a maintenance inspection 30 days prior to warranty expiration.

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1.0 INTRODUCTION

1.1 General Information

Read this manual carefully to learn how to operate and service your machine correctly. Failure to read this manual can result in personal injury or equipment damage.

This manual is a permanent part of your machine and should remain with the machine when you sell it.

Measurements in this manual are given in both customary U.S. units and metric equivalents. Use only correct replacement parts and fasteners. Metric and inch fasteners require appropriate tools to install.

NOTE: Right and left-hand sides are determined by facing in the direction the implement will travel when moving forward.

1.2 Serial Number

Record the serial number, model number, and model year of your harvester to help trace the machine should it be stolen. Your dealer also needs these numbers for all warranty claims and when you order parts.

The harvester serial number is found on the serial number plate which is located on the front of the left shield as shown in Figure 1.

Record your serial number, model number, and model year in the space provided below.

Serial Number:

Model Number:

Model Year:

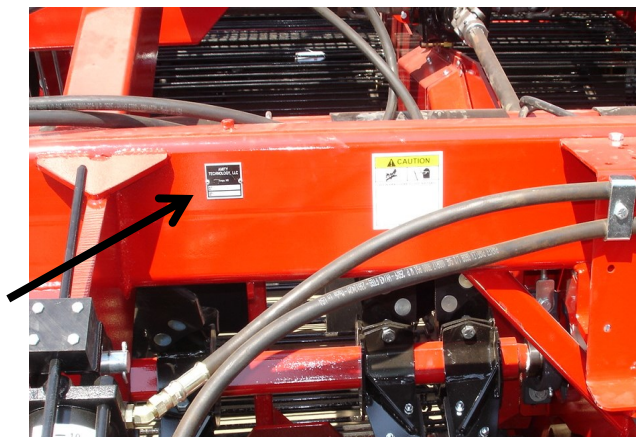


Figure 1: Serial Number Plate Location

2.0 SAFETY

2.1 Recognizing Safety Information in Manual

Figure 2 is the safety-alert symbol. When you see this symbol on your machine or in this manual, be alert to the potential for personal injury.

Follow recommended precautions and safe operating practices.



Figure 2: Safety-Alert Symbol

2.2 General Harvester Safety

You are responsible for the safe operation and maintenance of your Amity beet harvester. You and anyone else, who will operate, maintain, or work around the harvester should be familiar with the operating and maintenance procedures and safety information in this manual.

Safety practices protect you and the people around you, so make them a working part of your safety program.

Harvester owners must give operating instructions annually to operators or employees before allowing them to operate the harvester per OSHA regulation 1928.57.

The most important safety device on this equipment is a safe operator. It is the operator's responsibility to read and follow all safety and operating instructions in the manual. All accidents can be avoided.

A person who has not read and understood all operating and safety instructions is not qualified to operate the machine. An untrained operator exposes himself and bystanders to serious injury or death.

Do not modify the equipment in any way. Unauthorized modification may impair the function and/or safety and could alter the life and warranty of the product.


The following list is a set of safety guide lines to adhere to:

1. Read and understand the Operator's Manual and all safety signs before operating, maintaining, or adjusting the harvester.
2. Install and properly secure all shields and guards before operating.
3. Have a first-aid kit available and know how to use it.
4. Have a fire extinguisher available and know how to use it.
5. Clear the area of people and remove foreign objects from the machine before starting and operating.
6. Shift to park, disengage PTO, lower machine to ground, relieve hydraulic pressure, stop engine, remove ignition key, and wait for all moving parts to stop before servicing, adjusting, repairing or disconnecting.

6. Shift to park, disengage PTO, lower machine to ground, relieve hydraulic pressure, stop engine, remove ignition key, and wait for all moving parts to stop before servicing, adjusting, repairing or disconnecting.
7. Review safety related items with all operators annually.
8. Wear suitable ear protection for prolonged exposure to excessive noise.

Think **SAFETY!** Work **SAFELY!**

2.3 Maintenance and Operating Safety

1.  Read and understand all information contained in the Operator's Manual regarding maintenance, adjustment, and operation of the harvester.
2. Shift to park, disengage PTO, lower machine to ground, relieve hydraulic pressure, stop engine, remove ignition key, and wait for all moving parts to stop before servicing, adjusting, repairing, or disconnecting.
3. Keep hands, feet, clothing, and hair away from all moving and/or rotating parts.
4. Ensure that all tractor controls are in neutral before starting.
5. Never wear ill-fitting, baggy, or frayed clothing when working on or around the harvester.
6. Make sure that all guards and shields are properly installed and secured before operating the harvester.
7. Clear the area of all bystanders, especially children, when carrying out any maintenance or making adjustments on the systems or components.
8. Place stands or blocks under the frame before working beneath the machine.
9. Do not allow riders on the harvester or tractor during field operation or transport.
10. Never operate the harvester inside a closed building.
11. Stay away from overhead obstructions and power lines during set up and operation. Electrocution can occur without direct contact.

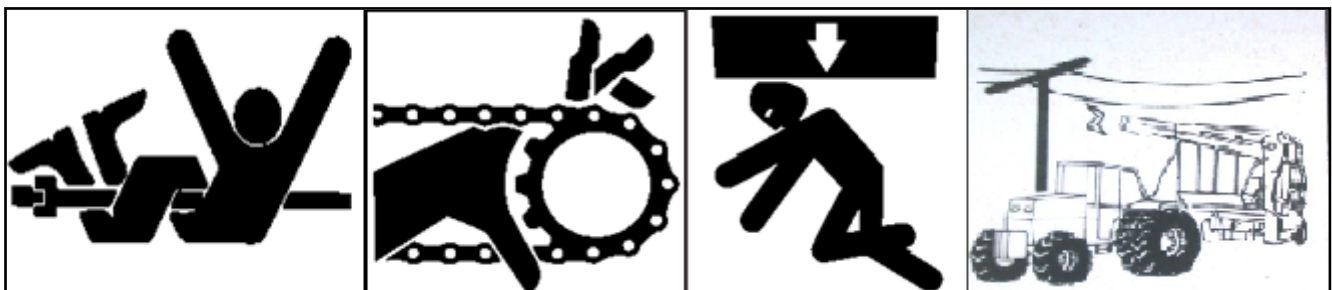


Figure 3: Maintenance and Operation Safety Symbols

2.4 Hydraulic Safety

1. Always place all tractor hydraulic controls in neutral before dismounting.
2. Make sure that all components in the hydraulic system are kept in good condition and are clean and tight.
3. Replace any worn, cut, abraded, flattened or crimped hoses and metal lines.
4. Do not attempt any makeshift repairs to the hydraulic lines, fittings, or hoses by using tape, clamps, or cements. The hydraulic system operates under extremely high-pressure. Such repairs may fail suddenly, creating a hazardous and unsafe condition.
5. Wear proper hand and eye protection when searching for a high-pressure hydraulic leak. Use a piece of wood or cardboard as a backstop instead of hands to isolate and identify a leak.
6. If injured by a concentrated high pressure stream of hydraulic fluid, seek medical attention immediately. Serious infection or toxic reaction can develop from hydraulic fluid piercing the skin surface.
7. Before applying pressure to the system, make sure all components are tight and that lines, hoses and couplings are not damaged.
8. On self-contained hydraulic systems, make sure that shut off valves are in open position before engaging PTO.



Figure 5: Hydraulic Safety Symbols

2.5 Transport Safety

1. Read and understand all information in the Operator's Manual regarding procedures and safety when operating the harvester in the field or on the road.
2. Make sure the Slow Moving Vehicle (SMV) emblem and required lights and reflectors are in place, clean, and can be seen clearly by all overtaking and oncoming traffic.
3. Do not allow riders on any part of the harvester during either field operation or travel.
4. Attach to the tractor using only a drawbar pin with provisions for a mechanical retainer.
5. Always attach a safety chain.
6. Always use hazard warning flashers when transporting unless prohibited by law.

7. Always lower elevator boom when transporting harvester.
8. Stay away from overhead obstructions such as power lines.
9. For max transport speed on smooth roads see section 3.2.

2.6 Safety Decals

The types of decals on the equipment are shown in the illustration below. Proper safety requires that you familiarize yourself with the various safety decals, the type of warning, and the area, or particular function related to that area, that requires your safety awareness.

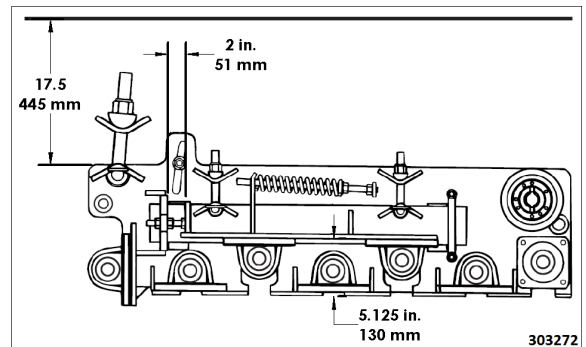
REMEMBER: If safety decals have been damaged, removed, become illegible, or parts are replaced without decals, new decals must be applied. New decals are available from your authorized dealer.

Cleaning Bed Adjustment:

Hazard: General safety alert

Avoidance: Read and understand the Operators Manual before operating the machine.

PN: 303272

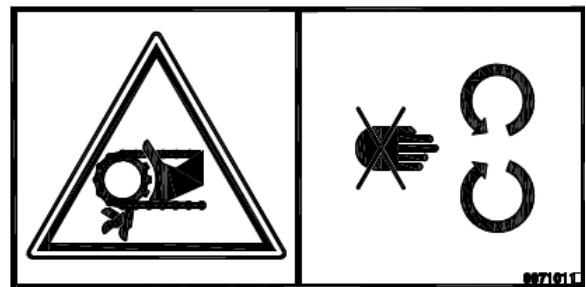


Warning / Moving Part:

Hazard: General safety alert

Avoidance: Read and understand the Operators Manual before operating the machine

PN: 9971011

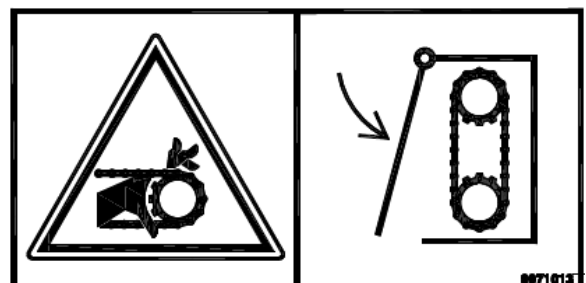


Warning / Moving Part:

Hazard: General safety alert

Avoidance: Read and understand the Operators Manual before operating the machine

PN: 9971013

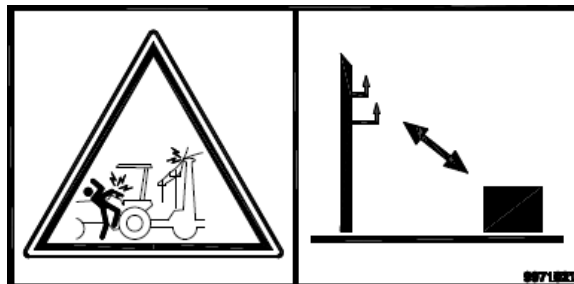


Warning / Electrocution:

Hazard: Electrical Shock Hazard – risk of personal injury or Death and component damage.

Avoidance: Stay clear of overhead power lines and other obstructions.

PN: 9971021

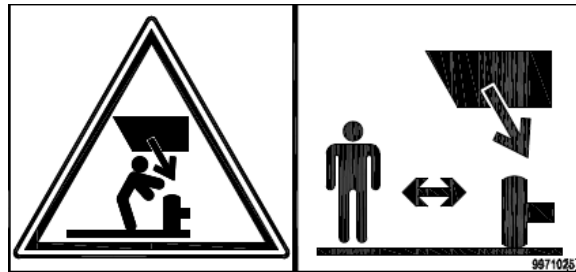


Warning / Overhead Lift Hazard:

Hazard: General safety alert

Avoidance: Stay clear of this area while engine and machine are operating

PN: 9971025

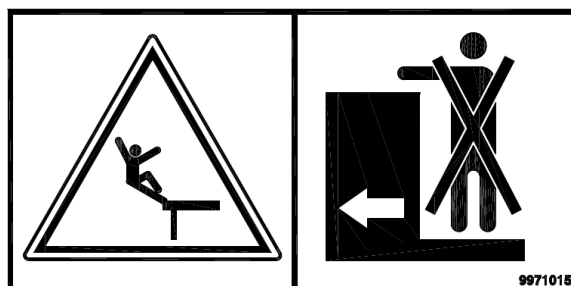


Warning / Falling Off Hazard:

Hazard: Falling off of machine.

Avoidance: Do not climb on the machine.

PN: 9971015

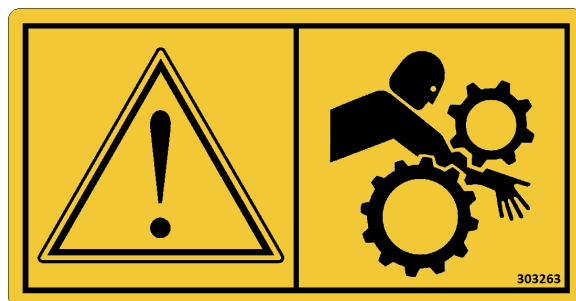


Danger / Moving Parts:

Hazard: Getting limbs or clothing stuck in machine.

Avoidance: Do not climb on the machine.

PN: 303263



Danger / Rotating:

Hazard: Electrical Shock Hazard – risk of personal injury or Death and component damage.

Avoidance: Read and understand the Operators Manual before operating the machine.

PN: 303268

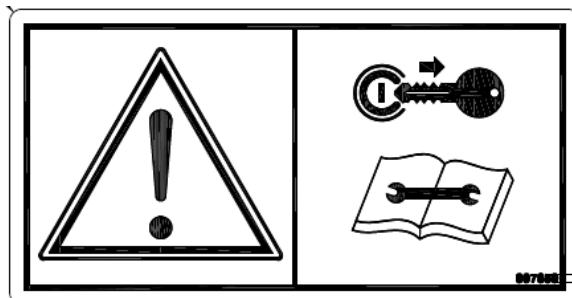


Warning / Engine off:

Hazard: General safety alert

Avoidance: Shut off engine and remove key before performing maintenance or repair work

PN: 997859



Warning / Falling Off Hazard:

Hazard: Falling off of machine.

Avoidance: Do not climb on the machine.

PN: 303277

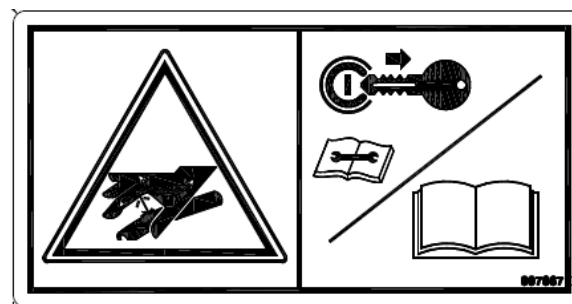


Warning / Falling Off Hazard:

Hazard: Falling off of machine.

Avoidance: Shut off engine, remove key, and relieve pressure before performing maintenance or repair work. Refer to the Operator Manual for proper service procedures.

PN: 997867

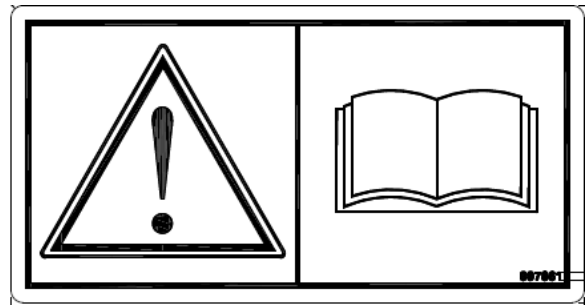


Warning / Read Operator Manual

Hazard: General safety alert

Avoidance: Read and understand the Operators Manual before operating the machine.

PN: 997861



Warning / Overhead Lift Hazard:

Hazard: General safety alert

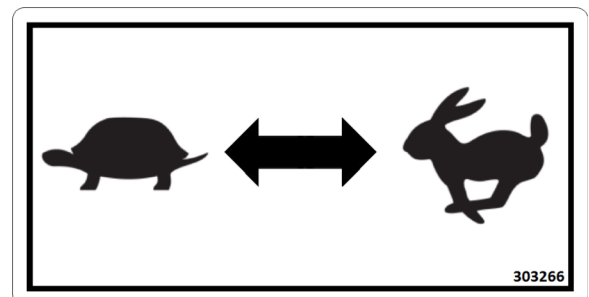
Avoidance: Read and understand the Operators Manual before operating the machine

PN: 303265



Slow—Fast

PN: 303266



3.0 SPECIFICATIONS

3.1 Harvester Specification

Table 3.1: Harvester Specifications

	Scrub	Wheel
Weight (Approx.)	45,000 lbs [20,400 kg]	45,500 lbs [20600 kg]
Tank Capacity	4.5 tons [4085 kg]	4.5 tons [4085 kg]
Recommended Working Speed	3-5 mph [4.8-8.1 kmh]	3-5 mph [4.8-8.1 kmh]
Transport Width (with boom down)	25' 4" [7.7 m]	25' 4" [7.7 m]
Operating Width (with boom up)	32' 8" [9.9 m]	32' 8" [9.9 m]
Length	32' 4" [9.8 m]	28' 4" [8.6 m]
Height	15' 11" [4.8 m]	15' 11" [4.8 m]

3.1.1 Tractor Specifications

Table 3.1.1: Tractor Specifications

	Scrub	Wheel
Minimum Horsepower	250 hp [186.5 kw]	250 hp [186.5 kw]
PTO Output	1000 RPM	1000 RPM
Spline Size	1-3/4in—20	1-3/4 in—20
Vertical Drawbar Load Est.	8000 lbs	8500 lbs
Minimum Hydraulic Capacity	30 GPM [114 L/m]	30 GPM [114 L/m]
Hydraulic Pressure	2700 PSI [18.6 Mpa]	2700 PSI [18.6 Mpa]
Number of Remotes	5 remotes or 4+ power beyond	5 remotes or 4+ power beyond

3.2 Traction: Front wheel assist (or 4 wheel drive) is recommended when pulling a harvester. In addition, front and/or rear weights may be necessary for balance, traction, and steering. Typically for a front wheel assist tractor, Amity recommends a minimum of 4,500 lbs (2041.7 kg) in rear weights and 2000 lbs (907.5 kg) in front weights.

Table 3.2: Tire Size, Pressure, and Lug Nut Torque

	Tire Size	Tire Pressure	Lug Nut Torque	Max Transport Speed
Non-steerable Axle	710/70R38	46 PSI [3.2 bar]	400-450 ft-lb [542.4-610.2 N·m]	25 mph [40 kph]
Steerable Axle	600/60R30.5	55 PSI [3.8 bar]	400-450 ft-lb [542.4-610.2 N·m]	25 mph [40 kph]
Non-steerable Axle	900 / 60R32	37 PSI [2.6 bar]	400-450 ft-lb [542.4-610.2 N·m]	25 mph [40 kph]
Track Axle	30" x 67" track	—	See Track Manual	15 mph [24 kph]

3.2.1 Hydraulic Flow Rates: Each hydraulic circuit for the harvester has a designated flow rate; approximate values are listed in the table below.

Table 3.2.1: Hydraulic Flow Rates

Circuit	Standard	Metric
Beet Tank	10 gpm	37.9 L/m
Row Finder	8 gpm	30.3 L/m
Lift	5 gpm	18.9 L/m
Active Depth Control (Open Center)	16 gpm	60.5 L/m
Active Depth Control (Closed Center)	6 gpm	22.7 L/m
Jump Chain (Wheel)	20 gpm	75.6 L/m

NOTE: Values listed are a good starting point; however, flow rates should be fine-tuned to allow the smallest flow rate possible while still providing enough power to run harvester properly.

4.0 PREPARATION

4.1 Tractor Preparation

4.1.1 Adjusting the Drawbar: The tractor drawbar must be set within the given range to maintain the integrity of the drive system. The range is shown in Figure 6.

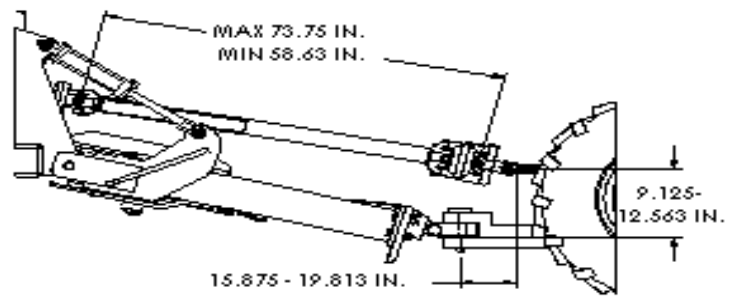


Figure 6: Drawbar Range

IMPORTANT: Ensure the driveline remains within operating range under all conditions.

4.1.2 Tire Spacing and Inflation: Tires should be inflated to the manufacturer's specification. See section Table 2: Tire Size and Pressure on page 7 for more information. Figure 7 shows the appropriate tire spacing.

$A = 4 * B$

B = Row Spacing

C = Tire Width, must be as narrow as possible.

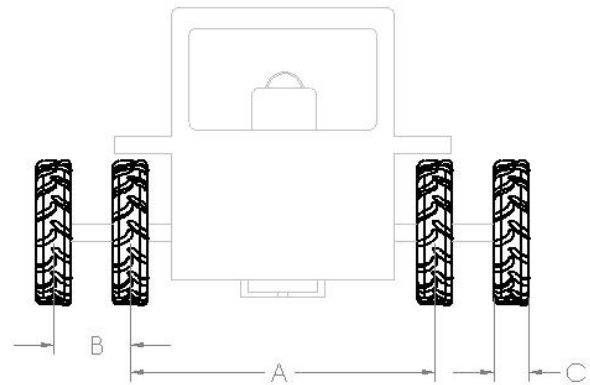


Figure 7: Tire Spacing

IMPORTANT: Tires must be narrow enough not to contact beets when driving down rows while still providing enough traction to pull the harvester.

NOTE: The Front tires must be aligned with the rear tires.

4.1.3 Three-Point Hitch Position: Three-point hitches cannot be connected to the hitch when using an Amity beet harvester. It must be fully raised or removed.

NOTE: Amity recommends removing three-point hitches.



CAUTION: Ensure the receiver and drawbar support arms clear the PTO driveline under all conditions.



Figure 8: Fully Raised Three-Point Hitch

4.2 Harvester Preparation

4.2.1 Lifter Strut Spacing: Verify the spacing matches the spacing of the planted crop as shown in Figure 9.

A=B/2 Center of frame to center of strut

B=Row spacing

C=Space appropriate for size of beets (This space is the pinch point)

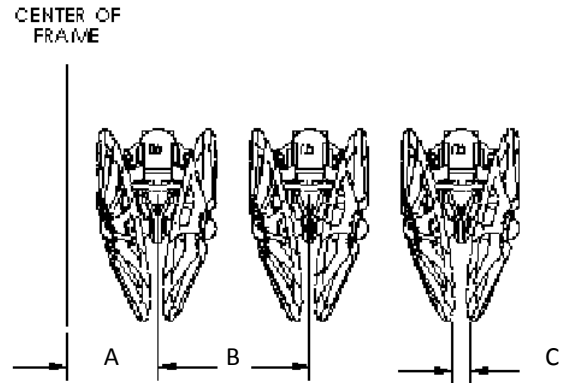


Figure 9: Lifter Strut Spacing

NOTE: Refer to Operating the Harvester section 6.9.1 for pinch point spacing guidelines.

4.2.2 Hydraulic Tank Oil Level and Valve Position: Refer to section 11.0, Lubrication and Maintenance, for the service schedule and oil type. “Full Cold Line” on the decal should be at the dimension shown in Figure 10.

! CAUTION: Valves (1 & 2) must be open prior to engaging the PTO, or system failure will occur. Valves in Figure 9 are shown in the open position.

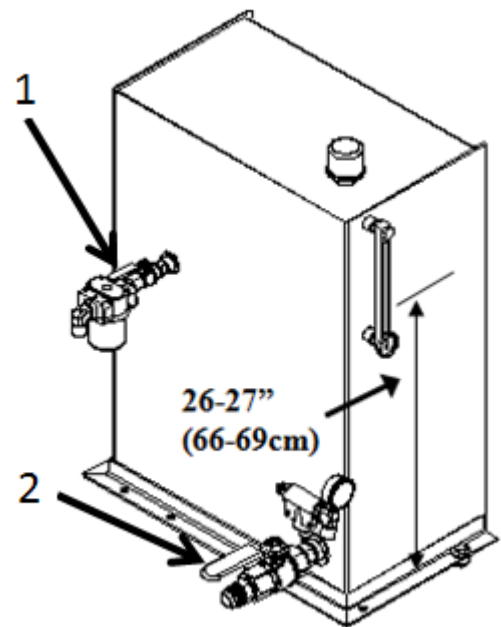


Figure 10: Hydraulic Oil Level

4.2.3 Scrub Control Box Wiring and Location: The scrub control box must be correctly wired and securely fastened in the tractor cab. The correct wiring is as follows:

White or Red wire- 12V Positive

Black wire- 12V Negative

NOTE: Locate the scrub box in a safe and secure location away from potential liquid spills.

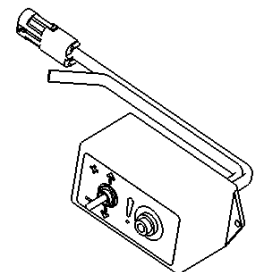


Figure 11: Scrub Control Box

The preferred method for attaching the control box to the tractor is to use a 12V switched source as shown in Figure 12.

When a 12V switched source is not available, an alternative way to attach the control box is shown in Figure 13.

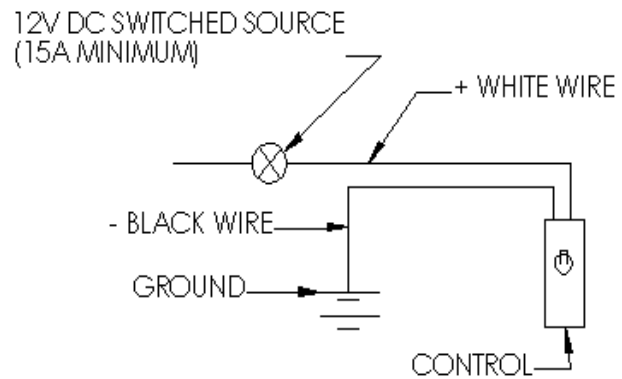


Figure 12: Preferred Wire Attachment Method

NOTE: Figure 12 shows the preferred method of attachment and should be used if at all possible.

CAUTION: When using the connection method shown in Figure 13, the control must be disconnected when not in use.

After wiring the control box to the tractor, the harness on the harvester must be wired to the actuator switch as shown in Figure 14.

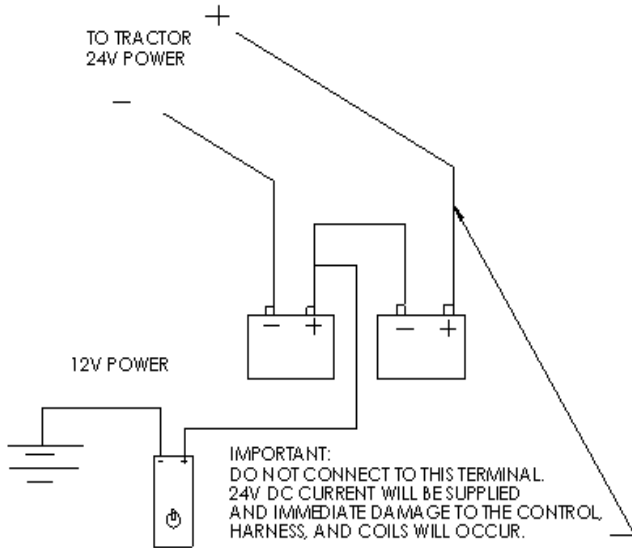


Figure 13: Alternative Wire Attachment Method

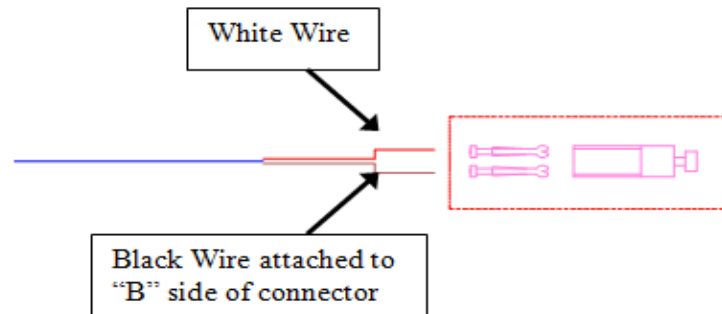


Figure 14: Wiring Harness to Actuator



4.2.4 Shield Placement: Before starting, be sure to secure the shields in operating position (closed position).

4.2.5 Gearbox Oil Level: Check all gearbox oil levels before operating. Refer to section 11.0, Lubrication and Maintenance, for oil type and fill level information.

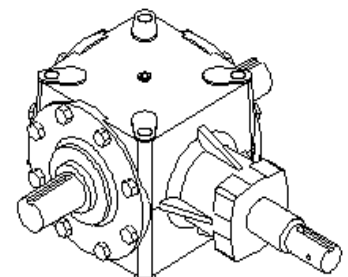


Figure 15: Gearbox

4.2.6 Greasing: Refer to section 11.0, Lubrication and Maintenance, for grease type and frequency requirements.

IMPORTANT: Use only hand held grease guns. Air-powered grease guns can damage your seals. Over greasing may also damage bearing seals. If damage due to over greasing occurs, replace the damaged seals immediately.

4.2.7 Attaching PTO to Harvester:

1. Remove the spring pin on the shield.
2. Slide the shield forward.
3. Connect the PTO to the spline shaft.
4. Lock the PTO in place using 2- $\frac{5}{8}$ in. bolts and nuts.
5. Slide and lock the shield into place.

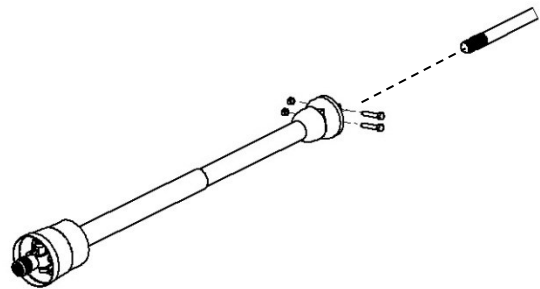


Figure 16: Attaching PTO to Harvester

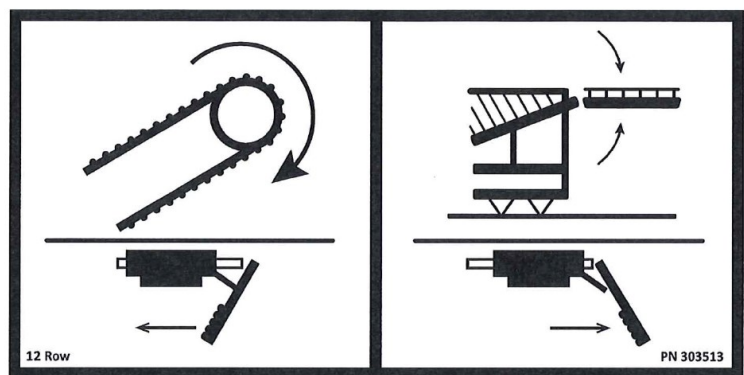
4.2.8 Raising Boom:

Once in the field, follow these steps before lifting beets.

1. Raise the boom.
2. Set the boom to the desired height by locking pins to one of the 4 holes on the support struts.
3. Lower the boom onto the pins to relieve hydraulic pressure on the hydraulic cylinders.
4. Move the selector valve to elevated position.



Figure 17: Lifted Boom



5.0 ATTACHING AND DETACHING

5.1 Attaching Hydraulic and Electrical Systems

Harvesters are available with ISO couplers or metric adapters. If the hydraulic attachments on your harvester do not fit the tractor, contact your Amity dealer.

CAUTION: To avoid injury from escaping fluid under pressure, relieve the pressure in the system before disconnecting or connecting hydraulic or other lines. Tighten all connections before applying pressure.

1. Connect all hydraulic lines to tractor as shown in Figure 18.
2. Connect the harvester warning light harness to the tractor. Make sure the harvester warning lights operate with the tractor warning lights and turn signals.
3. Connect the control monitor or switchbox to the harness routed into the tractor cab.



Figure 18: Attaching Hydraulic Lines

5.2 Attaching Harvester to Tractor Drawbar

1. Adjust the tractor drawbar (see Tractor Preparation, section 4.1.1)
2. Remove the tractor hitch pin.
3. Install required bushings into pull plate.
4. Adjust the hitch height.

- CAUTION:**
5. Shift to park, shut off the engine, and remove the ignition key before getting out of tractor.
 6. Line up the pull plate with the drawbar.
 7. Place hardened washer (A) between the drawbar and pull plate, and install shims as necessary (B).
 8. Reinstall the hitch pin.
 9. Connect the safety chain to the drawbar supporting structure.

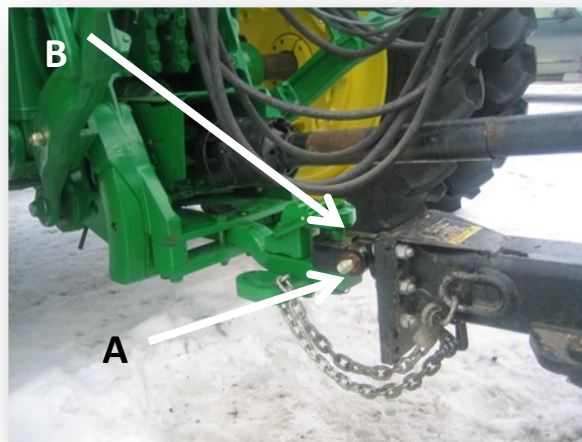


Figure 19: Attaching the Harvester to the Tractor Drawbar

5.3 Attaching PTO Driveline

CAUTION: To avoid bodily injury or death, shut off the tractor and lower the machine to the ground before attaching the PTO driveline.

IMPORTANT: Keep the driveline and powershaft splines clean of dirt, paint, and debris.



Figure 20: Attached PTO Driveline

- 1.** Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, and remove the ignition key.
- 2.** Raise the tractor PTO shield.
- 3.** Pull back on the PTO collar until it latches.
- 4.** Align the splines between the harvester driveline and the tractor PTO shaft. Push the driveline onto the shaft until the collar snaps forward on the yoke.
- 5.** To ensure the PTO is secure, pull back on the shield. Do not pull on the collar as this will release the latch.
- 6.** Lower the tractor PTO shield.

5.4 Using Stands

CAUTION: Always use stands when working on, near, or underneath the harvester.

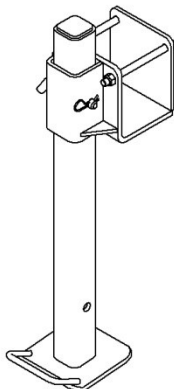


Figure 21: Amity Stand

6.0 OPERATING THE HARVESTER

6.1 Start Up

1. Ensure that yourself, bystanders, and all objects are clear of the harvester before starting.
2. Check the PTO to ensure it is not engaged.
3. Start the tractor and throttle down to idle.
4. Engage the PTO.
5. Throttle up to 1000 PTO RPM and ensure the boom is raised before lifting any beets.



CAUTION: The PTO must be turning if any beets are present on the grabroll bed or if the harvester is lifting beets. Engaging the PTO with a loaded grabroll bed can cause belt damage.

6.2 Field Operating Speed

The harvester should be operated at speeds specific to the conditions; typical speeds are 3-5 mph (4.8 -8 kmh).

Changing speed may affect the function of the machine creating the need for other operating adjustments. Refer to Troubleshooting, section 12.0, if problems occur.

6.3 Turning Radius

Turning at the end of the field while pulling the harvester requires a wide area. One way to accommodate the large turning radius is to plant headland rows. Amity recommends a minimum of 48 headland rows on each end of the field.

IMPORTANT: Failure to provide a sufficient turning radius for the tractor and harvester may lead to damage of the rowfinder assembly, active depth control wands, and/or tractor tires.

6.4 Break-in Period

After an initial 5 hours of normal field operation, check the apron chain tension and all fasteners, lug nuts, rollers, and lifter struts. Refer to section 7.0, Adjustments, if adjustments are required.

After checking the items listed above, do a general check of all major systems and components before continuing.

6.5 Field Cleaning

The harvester will collect mud at different rates during operation depending on soil conditions. It is important to clean the machine every two hours or more often if the conditions demand.

IMPORTANT: If left unclean, mud will clog the machine and cause imminent damage. Frequently clean the machine to avoid damage.

6.6 Lifter Struts

Amity offers two styles of lifter struts: steel spacer tubes that hold the lifter strut securely in position for lifting in normal soil conditions or an optional rubber bumper for use in rocky conditions. The rubber bumper compresses when the wheels strike a large rock and allow the assembly to move upward. The movement minimizes wheel damage.

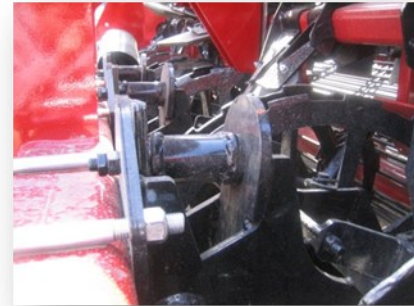


Figure 22: Lifter Struts

6.7 Leveling Adjustment

6.7.1 Manual: To obtain optimal performance of the harvester, the machine must be level from left to right and front to rear while harvesting. The rear struts can be adjusted to compensate for an un-level harvester. See section 7.1 for adjustment instructions.



Figure 23: Manual Leveling Adjustment

6.7.2 Automatic Depth Control (ADC): ADC is an optional feature that automatically adjusts the lifting depth for optimal performance. No manual depth adjustment is required if your Amity beet harvester has this feature.

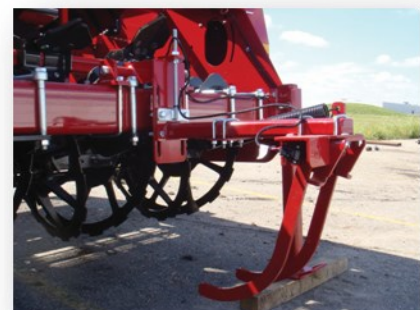


Figure 24: ADC Depth Wands

6.8 Row Finder

Amity harvesters have the option of a hydraulic row finder attachment. The Row finder helps keep the lifter struts directly in line with crop rows.



Figure 25: Row Finder

6.9 Digging Depth

Digging depth varies with soil and crop conditions. Three inches (7.62 cm) is a good starting point. Actual digging depth is best determined by checking the depth in several areas after harvesting 100 ft. (30 meters)

IMPORTANT: Though 3 in. (7.62 cm) is a good starting depth, the shallowest possible depth to lift whole beets should be used. Digging shallower will extend the life of the machine.

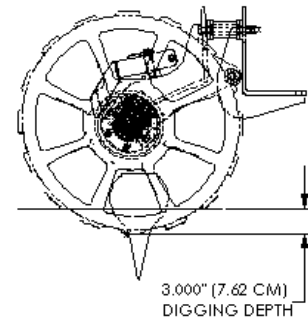


Figure 26: Digging Depth

6.9.1 Pinch Point Spacing and Position:

The pinch point position and spacing should be placed as to allow maximum beet yield while minimizing excess soil and debris from entering the machine. See sections 7.3 and 7.4 for adjustments.

6.10 Wheel Fillers

Optional wheel fillers can be bolted onto lifter wheels to lift more soil helping reduce beet damage in extremely dry conditions and loss of small beets through lifter wheel spokes.

IMPORTANT: Wheel fillers should only be used when necessary. Loading excess soil into machine can reduce machine life and lead to excess wear on components.

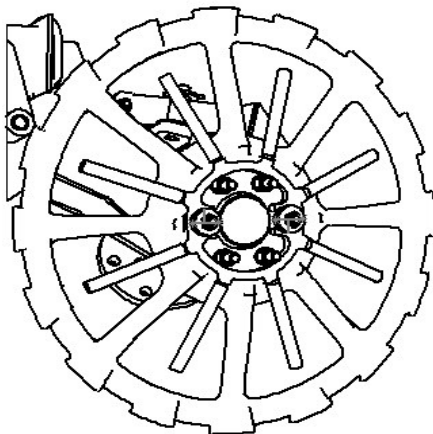


Figure 27: Lifter Wheel 53867 with Center Mount Wheel Filler

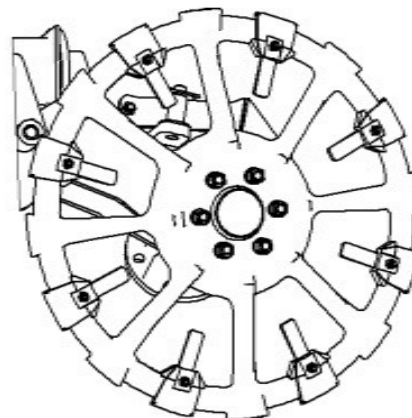


Figure 28: Lifter Wheel 69855 with Rim Mounted Filler Tabs. Note: Center mount wheel fillers also available on this lifter wheel.

6.11 Scrapers

Scrapers keep the Lifter Wheels clean by removing mud and dirt off the wheels. In turn, the Lifter Wheels are able to turn freely and lift beets.

Amity lifting struts are available with two types of scrapers, Top or Bottom. Bottom scrapers come standard with the Single Plate Strut. Top scrapers come standard on the Double Plate Strut.

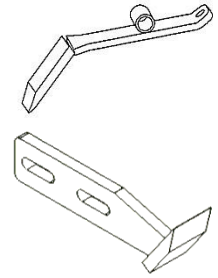


Figure 29: Above- Top Scraper, Below- Bottom Scraper

6.12 Paddles

Paddles are designed to transfer beets from the lifter wheels onto the apron chain.



Figure 30: Rubber Paddles



Figure 31: Plastic Paddles

Two types of paddles are available for your Amity beet harvester. Rubber paddles are required when using rock struts to lift beets and work well in standard soil conditions. Plastic paddles are available for better cleaning action in heavy, clay-based soils and cannot be used with rock struts. Figures 30 and 31 show the two styles of paddles.

Sections 7.7 and 7.8 have information regarding adjustments for paddles and the paddle shaft.

6.13 Apron Chain

The apron consists of several parallel sets of chains. The apron provides the first system to remove dirt, clods, and debris from the beets. See section 7.10.1 for proper apron chain tension.



Figure 32: Apron Chain

6.14 Grabroll Bed

Grabroll beds provide the majority of the cleaning action within the harvester. Grabrolls with scrolling provide an aggressive push to beets. Beets are continually turned and flipped over so that the entire beet is cleaned. Scrolled grabrolls will also thoroughly remove mud and break up dirt clods. The smooth grabrolls turn slightly faster than the scrolled, and provide a wedging action to remove dirt, tailings, and debris.

6.14.1 Front Grabroll Bed: The front grabroll bed separates trash and dirt from the beets while transferring beets to the center of the machine and onto the jump chains.

The smooth grabrolls are spring mounted to allow relief for rocks as they pass over the rolls. The bed has several adjustments to optimize cleaning and minimize beet damage. See sections 7.12 and 7.14 for front grabroll spacing and speed adjustments.



Figure 33: Front Grabroll Bed

6.14.2 Rear Grabroll Bed: The rear grabrolls provide additional cleaning while transferring beets to the rear, center of the harvester to discharge them into the scrub.

As with the front grabroll bed, the smooth grabrolls are spring mounted to allow relief for rocks as they pass over the rolls. Kickers, welded to the scrolled rolls, kick the beets to keep them moving on the grabroll bed. The beets can take full advantage of 75 sq. ft. (6.96 sq. m.) of cleaning potential. Refer to sections 7.17, 7.18, and 7.19 for adjustments.



Figure 34: Rear Grabroll Bed

6.15 Extended Jump Chain Option

Extended jump chain is an option in lieu of rear grabrolls. Instead, the jump chain continues where the grabrolls would be placed. This option is intended for harvesting in lighter soils and offers a gentler handling of the beets.

6.16 Wheel Option

The wheel option is available for those whose soil is lighter or who do not want chains. The bed consists of the standard jump chain.



Figure 35: Wheel Harvester

6.17 Scrub Chain

The scrub chain lifts beets from the rear grabrolls to the tank.

The inside chain typically runs faster than the outside chain providing additional cleaning.

NOTE: The larger the difference in the chain speed, the greater the chance of additional damage to the beets.



Figure 36: Scrub Chain

6.18 Machine Shutdown

1. To ensure maximum life of the machine, follow this procedure when stopping:
2. Raise the harvester out of ground with the PTO still engaged. Continue running the PTO at 1000 RPM until the grabroll bed is empty, and the harvester is completely clear of beets.
3. Once there are no beets left in harvester, throttle the tractor down to idle, and disengage the PTO.



CAUTION: When shutting down or reducing ground speed, the PTO must remain turning at 1000 RPM until the harvester is completely clear of beets. Failure to allow necessary time for the machine to cycle through beets will result in imminent damage to the drivebelt, and/or other components.

7.0 ADJUSTMENTS

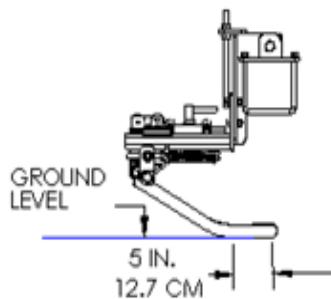
7.1 Manual Leveling

1. Raise the rear of the harvester with the hydraulic cylinders.
2. Add or remove cylinder stops as necessary.
3. Lower the rear of the harvester onto the stops.

NOTE: A 1 in. (2.5 cm) stop in a rear cylinder provides approximately 1 in. (2.5 cm) of lift in the corresponding front side.

NOTE: The harvester might not be level as a result of the weight of the extended boom. Adjusting the rear struts will help solve this problem.

7.2 Row Finder



When harvesting, the row finder wands should be adjusted like Figure 37 such that there is 5 in. (12.7 cm) of contact between the ground and row finder wands. Adjustment spring (B), shown in Figure 38, can be adjusted to apply more down pressure to ensure constant contact with the beet row.

Likewise, the row finder wands should be angled down when lifted out of the ground as shown in Figure 38. Dimension (A) can be adjusted using nuts (D):

Figure 37: Row Finder Wand Placement

1. To increase distance (A), adjust nuts (D) along line (F) toward the rear of the machine.
2. To decrease distance (A), adjust nuts (D) along line (F) toward the front of the machine.

Adjusting Height (E):

1. To change height (E) of the row finder, loosen bolts (C).
2. Adjust jam nuts (G) to desired height.
3. After adjusting height (E), retighten bolts (C).

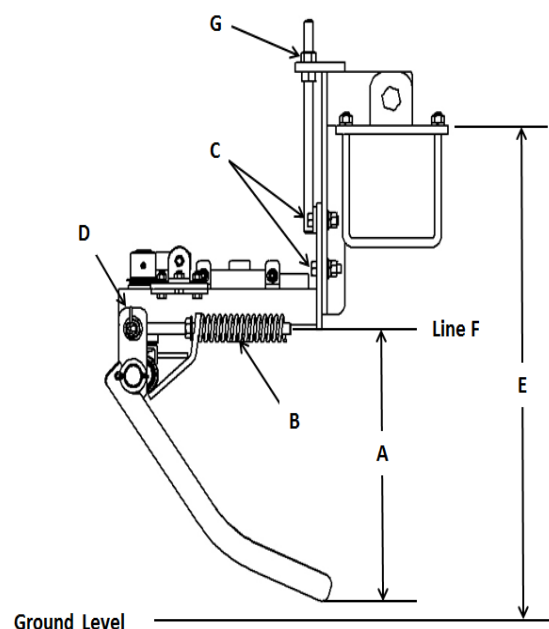


Figure 38: Row Finder Adjustment- Right Side View

NOTE: The wands should be angled down slightly when the machine is out of the ground. This will create down pressure from spring (B) when the machine is lowered to digging depth.

7.3 Pinch Point Position

The pinch point position can be adjusted by spacer (G), part number 50139. In muddy conditions, roll the pinch point forward by adding spacers. This will pop the beet faster with less mud. For dry or hard digging conditions, roll the pinch point back by removing spacers giving the wheels a longer time to lift the beet and reduce breakage in the ground. The extra dirt will lift the beets high enough for the paddles to send them into the machine. To adjust the pinch point position:

1. Loosen the two nuts on the front of the strut.
2. Add or remove spacers (G) to adjust the pinch point forward or back.
3. Retighten the hex nuts when desired position is reached.

NOTE: The addition of 1 spacer (G) will decrease the pinch point height by ½ in. (1.3 cm) and 2 spacers by 1 in. (2.5 cm). Numbers are approximate.

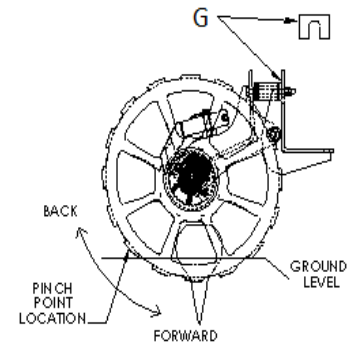


Figure 39: Pinch Point Adjustment

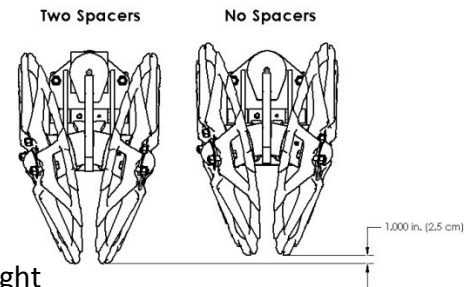


Figure 40: Pinch Point Height

7.4 Pinch Point Width

Matching pinch point to crop size is important to maximize yield and minimize tear. If the pinch point is too wide, smaller roots may be left in the ground resulting in a larger digging depth. In turn, more dirt will be put in the harvester. If the pinch point is too narrow, larger roots may be sliced. The pinch point width is adjusted by changing the quantity of half-moon spacers (B), part number 50747. To add or remove spacers:

1. Loosen the hex nuts holding the lifter wheel tight to the hub. Only the center bolt on the half-moon spacer is required to be removed. Adjust the other half of the spacer to allow another spacer to be added or removed.
2. Add or remove spacers (B) as necessary. It is most common to work in sets of 4 half-moon spacers.
3. Retighten the lifter wheel bolts.

NOTE: The addition or subtraction of 1 spacer (B) will add or subtract .1875 in. (4.8 mm), respectively, from the pinpoint width.

IMPORTANT: As a general rule, the pinch point spacing (A) should be adjusted as shown in Table 5.

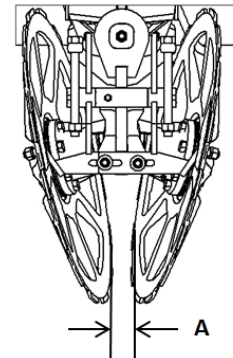


Figure 41: Pinch Point Width

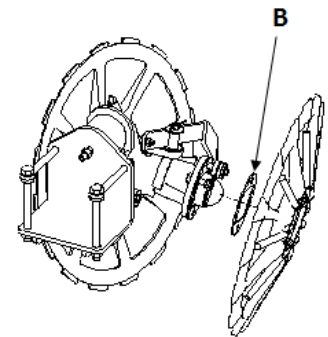


Figure 42: Pinch Point Spacer Adjustment

Table 5: Pinch Point Width

Pinch Point Width	Average Beet Weight
1 ½ - 1 ¾ in. [3.8-4.4 cm]	.9-1.2 lb. [.41-.54 kg]
1 ¾ - 1 ⅞ in. [4.4-4.7 cm]	1.1-1.5 lb. [.50-.68 kg]
1 ⅞ - 2 in. [4.7-5.0 cm]	1.3-1.7 lb. [.59-.77 kg]

7.5 Wheel Fillers

7.5.1 Adding or Removing Center Mount Wheel Fillers:

1. Remove the lock nut, lock washer, and flat washer from bolts (B) as shown in Figure 44.
2. Add or remove the center mount wheel filler.
3. Replace the fasteners.

NOTE: If bolts (B) are removed, they must be reassembled in holes (C) shown below in Figure 45. The bolts must line up exactly in line with the opposite spokes of the lifter wheels or they will not line up correctly on the wheel fillers.

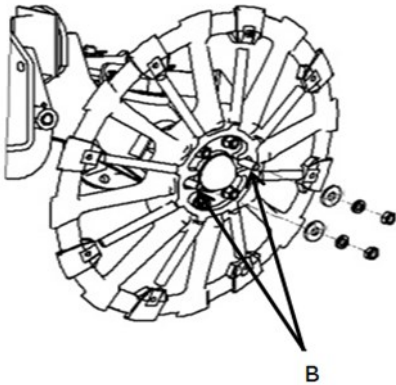


Figure 43: Adding or Removing Center Mount Filler Wheels

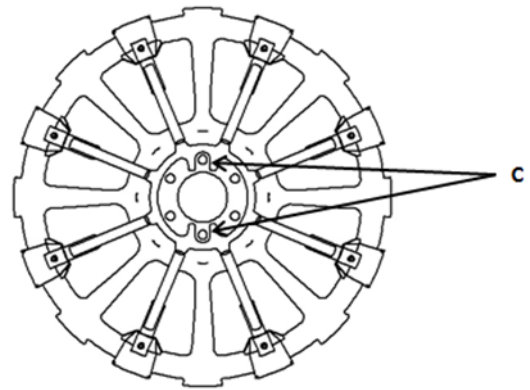


Figure 44: Center Mount Wheel Filler Hole Alignment

7.5.2 Adding Rim Mount Filler Tabs:

1. Insert the filler tab into the slot on the backside of the lifter wheel.
2. Fasten with a bolt and nut as shown in Figure 45.
3. Repeat steps 1 and 2 for the remaining 7 tabs.

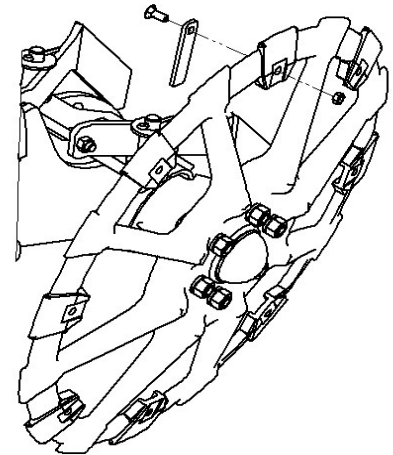


Figure 45: Adding or Removing Rim Mounted Filler Tabs

7.6 Scrapers

7.6.1 Top Scraper: Adjust bolt (A) to move scrapers out to the lifter wheels.

7.6.2 Bottom Scraper:

1. Loosen bolts (B).
2. Adjust scrapers to the desired position.
3. Tighten bolts (B).

NOTE: The lifter wheels must rotate a full 360° after adjusting the scrapers to ensure clearance.

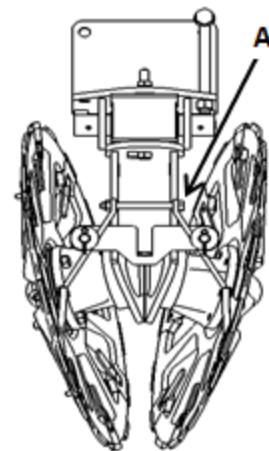


Figure 46: Top Scrapers

7.7 Paddle Shaft Position

When operating with a steel spacer in the lifter strut, set the paddle shaft to clear the lifter wheel rims to ensure that all beets get moved to the apron chain.



CAUTION: When the harvester is equipped with rock struts, distance (C), the distance between the lift wheels and paddle shaft, should be a minimum of 1 in. (2.5 cm) more than the digging depth to protect the paddle shaft from the lifter wheels in the event of contact with a rock.



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Lower machine onto stands or blocks to take weight off the lifter wheels.
3. Open the left and right access doors and latch them.
4. Loosen the bearing mounting bolts and the jam nuts on the adjusting bolts.
5. Measure the distance between the paddle shaft and the rim of the lifter wheels.
6. Turn the adjusting bolt to give a minimum of 1 in. (2.5 cm) more than the digging depth of the machine. This dimension is critical, especially when using rubber bumpers (rock struts).

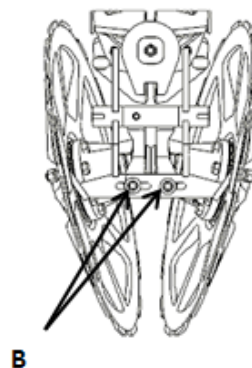


Figure 47: Bottom Scraper

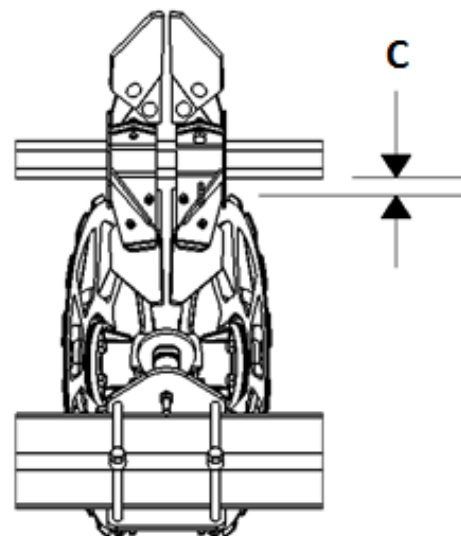



Figure 48: Paddle Shaft to Lifter Wheel Rim Dimension

NOTE: It may be necessary to readjust the apron/paddle shaft chain tension on both sides to provide slack to allow the paddle shaft to move.

7. Tighten the shaft mounting bolts and the jam nuts on the adjusting bolts. Set the same dimension (B) on both sides and secure the mounting fasteners in position. On wide-frame harvesters, set the same dimension (B) on the center mount as on the outer mounts.
 8. For harvesters equipped with rock struts, place a 4 x 4 in. (8.9 x 8.9 cm) block of wood under one of the lifter wheels and lower the entire weight of the machine down on this strut.
 9. The rim should clear the shaft by at least ½ in. (1.3 cm). If the rim is touching the shaft, raise the paddle shaft until it clears by at least ½ in. (1.3 cm).
 10. If the bumper compression is adjusted, raise the wheel off the block and lower it again. Check the clearance again.
 11. Repeat the procedure with each set of lifter wheels. This will ensure that none of the wheels will contact the paddle shaft.
-  12. Close and latch the access doors before starting the machine.

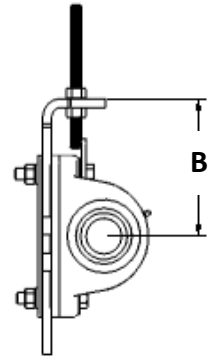


Figure 49: Apron/Paddle Shaft Chain Tension

7.8 Paddles

The paddles are adjustable, in and out, depending on wet or dry harvest conditions. Moving paddles toward the wheels will clean the rim of the wheel and aid in rotation. Adjusting the paddles in or out should be done after making any paddle shaft height adjustments.

IMPORTANT: Excess contact may stop lifter wheel rotation.

7.8.1 Rubber Paddles:

1. Loosen lock nuts (C) on the paddle mounts.
2. Move the paddles to the desired position.
3. Tighten lock nuts (C).



Figure 50: Rubber Paddle Adjustment

7.8.2 Plastic Paddles:

1. Loosen lock nuts (D) on the backside of the paddles.
2. Move the paddles in or out for the desired position.
3. Tighten lock nuts (D).

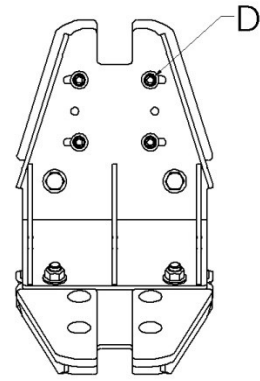


Figure 51: Plastic Paddle Adjustment

7.9 Apron and Paddle Drive Chain

7.9.1 Drive Chain Tension:



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.

2. Open the access door and latch it.
3. Loosen the chain idler sprocket (A).
4. Move the adjustment rod until the chain is at the desired tension (see section 7.16.1 for the chain tension).
5. Tighten the idler sprocket and recheck the chain tension.



6. Close and secure the access door before starting the machine.

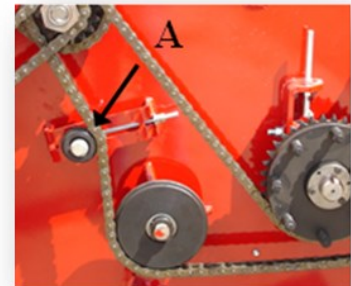


Figure 52: Chain Idler Sprocket

7.9.2 Replacing Drive Chain:

1. Follow steps 1-3 from above.
2. Remove the old chain and install a new chain.
3. Move the adjustment rod until the chain is at the correct tension (see section 7.16.1 for the chain tension).
4. Tighten the idler sprocket and recheck the chain tension.
5. Lubricate the chain if necessary (see Lubrication and Maintenance, section 11.0).



6. Close and secure the access door before starting the machine.

NOTE: Use a straight edge across the faces of the sprockets to determine their alignment. If they are not aligned, loosen the sprockets, realign, and tighten the sprockets.

7.10 Apron Chain

7.10.1 Apron Chain Tension: Tension of the apron chain should not be excessively tight; however, the chain should never drag on the ground or droop enough on the top to allow beets to be lost out the sides of the machine. To adjust the chain:

- ⚠ 1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
- 2. Open the left and right access doors and latch them.
- 3. Adjustments on the apron chain tension are made by first: removing or adding links and last: moving the front idler shaft.
- 4. To adjust the shaft, loosen the jam nuts holding the adjustment rods on the bearing mounting arms.
- 5. Use the adjusting rod and slide the bearing mounting arms apart or together.

NOTE: Adjusting the lower shaft too close to the lifter wheels can cause loss of beets. Removing slack from the chain with this adjustment is not advised.

- 6. Always measure the dimension between the shaft centers when making adjustments, keeping the dimension equal on the left and right sides.

NOTE: Apron chain is a high wear item, and links may need to be replaced frequently.

NOTE: Distance (A) between top and bottom chain should be kept at 11-12 in. (27.9 – 30.5 cm) measured from the centerline of chains.

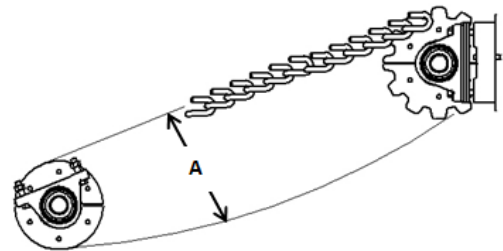


Figure 53: Distance between Top and Bottom Chains

- 7. Tighten the jam nuts on the adjusting rods, and be sure the adjusted apron chain does not contact the lifter wheels.
- ⚠ 8. Close and secure the access door before starting the machine.

NOTE: Machines with rubber paddles have zero spacers installed on the lower apron shaft (see Figure 54). Machines with plastic paddles have 4 spacers installed on the lower apron shaft with additional spacers included in the hardware kit.

7.10.2 Replacing Apron Chain:

- ⚠ 1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.

2. Open the left and right access doors and latch them.
3. Loosen the jam nuts holding the adjustment rods on the bearing mounting arms.
4. Slide the front bearing mounting arms backward to its loosest position.
5. Rotate the shafts until the splice link is accessible, and then disconnect the chain on both ends of the link.
6. Remove the apron chain or attach the new chain to the old chain before its removal. Use it to thread the new chain over the sprockets.
7. Thread a new chain over the sprockets, bringing the ends together.
8. Hook the ends of the chain together.
9. Repeat steps 5-8 for each apron chain.
10. Use the adjusting rod to slide the lower apron shaft into position to give the required tension, making sure the apron chain does not contact the lifter wheels.
11. Always measure the dimension between the shafts when tensioning. Keep them equal on the left and right hand sides.
12. When correctly positioned, tighten the jam nuts on the bearing mounting arm adjustment rods.
13. Latch the access doors on both sides before starting the machine.

7.11 Front Drive Belt

7.11.1 Belt Tension:

1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Open the access door and latch it.
3. Adjust the nut (B) until spring length (A) is 13.5 in. (34cm).
4. Lock double nuts (B).
5. Close and secure the access door before starting the machine.

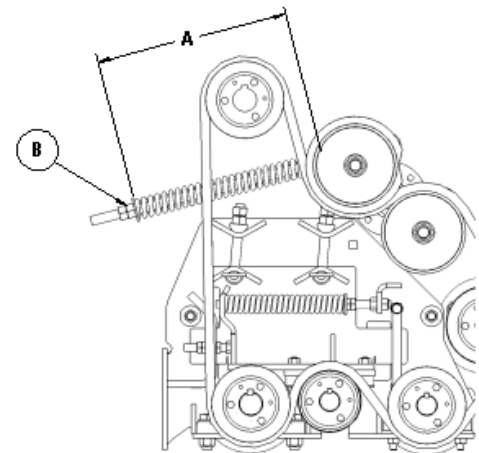



Figure 54: Front Drive Belt Adjustments



7.11.2 Replacing Belt:

1. Follow steps 1 & 2 from above.
2. Loosen nut (B) until the belt is loose.
3. Remove the old belt and install a new belt.
4. Tighten nut (B) until spring length (A) is 13.5 in. (34 cm).
5. Lock double nuts (B), and check the alignment of the sheaves.

-  6. Make sure belt is in the proper grooves, and secure the access door before starting the machine.

7.12 Front Grabroll Spacing

Adjusting the space between grabrolls will cause the beets to be cleaned at differing degrees. Mud-dier conditions may require more cleaning than dry conditions. To increase the cleaning action, increase the grabroll gap between #1 and #2.

-  1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Open the access door and latch it.
 3. Adjust nuts (B) to change the gap between smooth grabroll (A) and the scrolled grabrolls.
 4. Readjust the drive belt to the proper tension (see also section 7.11.1).
 5. Adjust nuts (D) to readjust rock trip spring compression (C) to 8.5 in. (21.7 cm).
-  6. Close the access door and latch it.

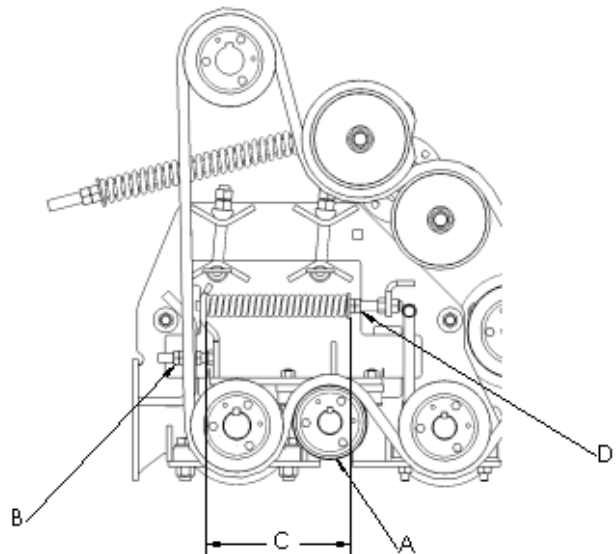


Figure 55: Front Grabroll Spacing Adjustment

IMPORTANT: Grabrolls must not touch each other under any operating conditions.

7.13 Grabroll Speed



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Open the access door.
3. Remove the grabroll bed drive belt according section 7.11.2 for the front drive belt or section 7.20.2 for the rear drive belt.
4. Remove the sheave by first removing sheave bolts.
5. Install the sheave bolts in the previously unused holes in the taper lock hub. Evenly tighten bolts until the sheave is loose.
6. Remove the taper lock hub, key, and sheave from the shaft.
7. Replace the drive sheave to obtain the desired grabroll bed speed. Refer to Table 6 for grabroll RPMs and part numbers.
8. Place the sheave on the shaft.

IMPORTANT: Ensure tapered surfaces are clean and free of all lubricants.

9. Place the taper lock hub on the shaft, and then insert the key into the shaft and hub.
10. Start the bolts through the taper lock hub into the sheave.
11. Align sheave (A) with the other sheaves and tighten evenly. Be sure the sheaves are aligned with each other after tightening.
12. Reinstall the grabroll bed drive belt.



13. Close and latch the access door before starting the machine.

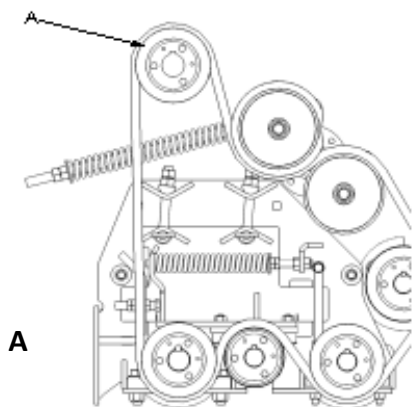


Figure 56: Front Grabroll Speed Adjustment

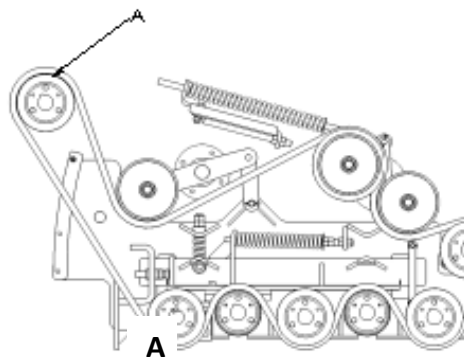


Figure 57: Rear Grabroll Speed Adjustment

NOTE: Grabroll tubes turn at 552 RPM from the factory unless ordered otherwise. A larger shaft sheave is available to speed the rolls to 606 RPM if mud collects on the grabrolls in muddy conditions. A smaller drive sheave is available to slow down the grabrolls to 500 RPM during dry conditions to reduce crop damage. See Table 6 for sheave dimensions and part numbers.

Table 6: Grabroll Tubes

Sheave A	Outside Diameter	Roll RPM	P/N
6.8*	7.15 in 182 mm	606	56647
6.2	6.55 in 166 mm	552	56646
5.6*	5.95 in 151 mm	500	53668

*Available from your authorized Amity dealer



7.14 Rock Trip Spring



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Open the access door and latch it.
3. Adjust nut (B) so dimension (C) is 8.5 in. (22 cm). (*See previous page)
4. Close the access door before starting machine.

7.15 Roller Chain Tension and Replacement

Roller chains need to be tightened when they are worn or when they jump sprocket teeth.

Each chain has a certain amount of allowable chain movement. To measure the chain movement, hold a tape measure up to the chain, then pull the chain down and then up. (The total amount of movement the chain moves should fit the specifications listed within the following sections). When servicing or replacing roller chains, reset the chain to factory specifications.

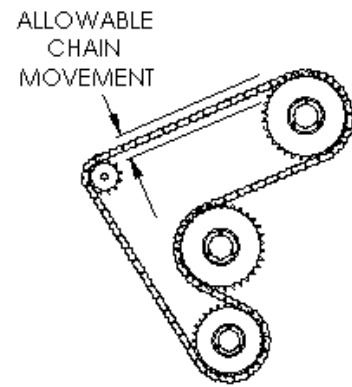


Figure 58: Allowable Chain Movement

Check the alignment of the sprockets periodically during the season and whenever replacing roller chains. To check alignment, lay a straight edge along a machined surface of the sprockets. If there is any misalignment, adjust the sprocket. For sprockets on a shaft with end float, align the sprocket for the normal operating position.

Install the replacement chain around both sprockets, bringing the free ends together on one sprocket. Insert a connector link and secure in place.

IMPORTANT: Recheck chain tension after an initial 5 hours of operation.

7.15.1 Paddle Shaft Chain:



Figure 59: Paddle Shaft Chain Tension

Paddle Shaft chain has 1 ½ to 2 in. (3.8-5.1 cm) of allowable chain movement as shown in Figure 61.

7.15.2 Jump Chain:



Figure 60: Jump Chain Tension

Jump Chain has $\frac{1}{2}$ to $\frac{3}{4}$ in. (1.3-1.9 cm) of allowable chain movement as shown in Figure 60.

7.15.3 Grabroll Bed Chain:

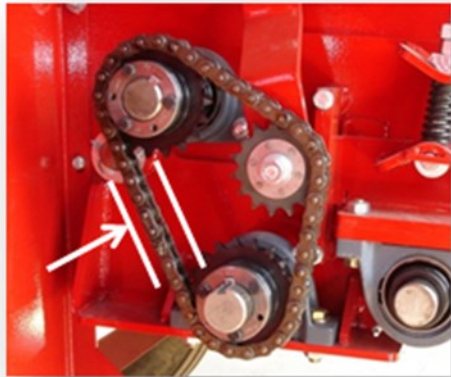


Figure 61: Grabroll Bed Chain Tension

Grabroll Bed Chain has $\frac{1}{2}$ to $\frac{3}{4}$ in. (1.3-1.9 cm) of allowable chain movement as shown in Figure 61.



Figure 62: Drive and Apron Shaft Chain

7.15.4 Drive Chain and Apron Shaft Chain:

Drive Chain (A) has 1 $\frac{1}{2}$ to 2 in. (3.8-5.1 cm) of allowable chain movement.

Likewise, Apron Shaft Chain (B) has 1 $\frac{1}{2}$ to 2 in. (3.8-5.1 cm) of allowable chain movement.

Both chains are shown in Figure 62.

7.16 Smooth Grabroll Height

Smooth grabroll height adjustments affect the amount of time beets remain on the grabrolls cleaning as well as the effectiveness of the cleaning. Decreasing the height of the grabrolls to below that of the scrolled grabrolls will increase cleaning ability by increasing the scrolling grabroll aggressiveness.

- 1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
- 2. Open the access door and latch it.
- 3. To adjust smooth grabrolls (H) up or down, use eye bolts (I).
- 4. Readjust the drive belt to the proper tension (see section 7.20.1)
- 5. Close the access door and latch it.

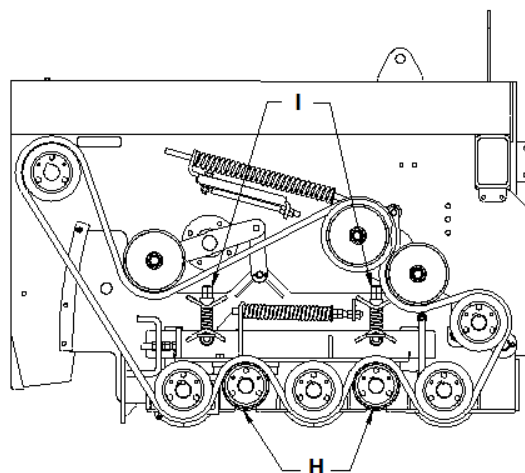


Figure 63: Smooth Grabroll Height Adjustment

7.17 Rear Grabroll Spacing

- 1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
- 2. Open the access door and latch it.
- 3. Adjust bolt (F) to change the gap between the smooth grabrolls and scrolled grabrolls.

NOTE: To set the gap between the grabrolls to original factory spacing, adjust bolt (F) so (G) is 2 in. (5 cm).

- 4. Readjust the drive belt to the proper tension (see section 7.20.1)
- 5. Readjust rock trip spring compression (C) to 8.5 in. (21.7 cm).
- 6. Close and latch the access doors before starting the machine.

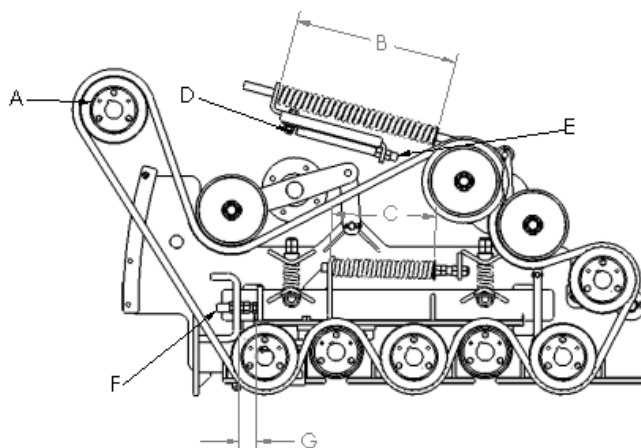


Figure 64: Rear Grabroll Spacing Adjustment

IMPORTANT: Grabrolls must not touch each other under any operating conditions.

7.18 Grabroll Bed Angle

Increasing the angle of the rear grabroll bed will increase cleaning time; likewise, decreasing the angle will decrease the cleaning time. To change the angle of the bed:



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Adjust ratchet jack (C).

NOTE: To level the grabroll bed, set (C) at 24 in. (61 cm).

NOTE: If your Amity harvester is equipped with the optional Hydraulic Rear Grabroll Adjustment, no manual adjustment is required.

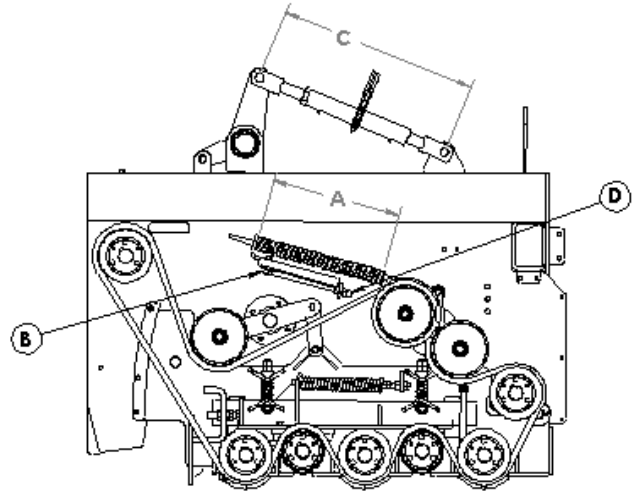


Figure 65: Grabroll Bed Angle and Rear Drive Belt Adjustment

7.19 Rear Drive Belt

7.19.1 Belt Tension:



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Open the access door and latch it.
3. Loosen bolt (B) on the adjustment slide.
4. Adjust the adjustment rod (D) until spring length (A) is 13.5 inches (34 cm).
5. Tighten bolt (B).



6. Close and latch the access door before starting the machine.

7.19.2 Replacing Belt:

1. Follow steps 1-3 from above.
2. Loosen adjustment rod (D) until the belt is loose.
3. Remove the old belt and install a new belt.
4. Tighten adjustment rod (D) until spring length (A) is 13.5 in. (34 cm).
5. Tighten bolt (B), and check alignment of the sheaves.
6. Make sure the belt is in the proper grooves, and secure the access door before starting the machine.



7.20 Grabroll Drive Chain



7.20.1 Chain Tension:

1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Open the right access door and latch it.
3. Loosen chain idler sprocket (E).
4. Slide the sprocket upward until the chain is at the proper tension (see section 7.16.4).
5. Tighten idler sprocket (E).
6. Close and secure the access door before starting the machine.

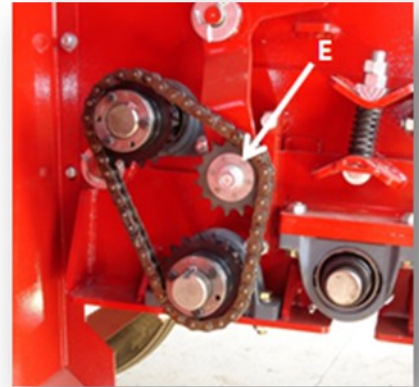


Figure 66: Grabroll Drive Chain Adjustment



7.20.2 Replacing Chain:

1. Follow steps 1-3 from above.
2. Slide the sprocket down until the chain is loose.
3. Remove the old chain and install a new chain.
4. Slide the idler sprocket upward until the chain is at the proper tension (see section 7.16.4).
5. Tighten idler sprocket (E).
6. Lubricate the chain if necessary (see Lubrication and Maintenance, section 11.0).
7. Close and secure the access door before starting machine.

NOTE: Use a straight edge across the faces of the sprockets to determine their alignment. If they are not aligned, loosen sprockets, realign, and then retighten the sprockets.





7.21 Reverse Grabroll #4

Grabrolls #2 and #4 come set to spin in the same direction as the tractor wheels (opposite grabrolls # 1, 3, and 5).

In dry conditions, to reduce beet damage, a kit is available to make grabroll #4 spin in the same direction as rolls #1, 3, and 5.

7.21.1 Installing Reverse Grabroll Kit (For 6 row/22 inch and 12 row/22 inch harvester):

-  1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Open the access door and latch it.
3. Remove the drive belt.
4. Remove sheave (A) from grabroll #4 and attach to the harvester frame using the stub shaft included in reverse #4 kit (B).
5. Install idler pulley (E) onto grabroll #4 shaft. Tighten both the lock rollers.
6. Attach sprockets (C) to the shafts on grabrolls #4 and #5 using hubs provided.
7. Reinstall the drive belt with the correct tension (see section 7.20.2).
8. Install drive chain (D) over the sprockets on grabrolls #4 and #5.
-  9. Close and secure the access door before starting.

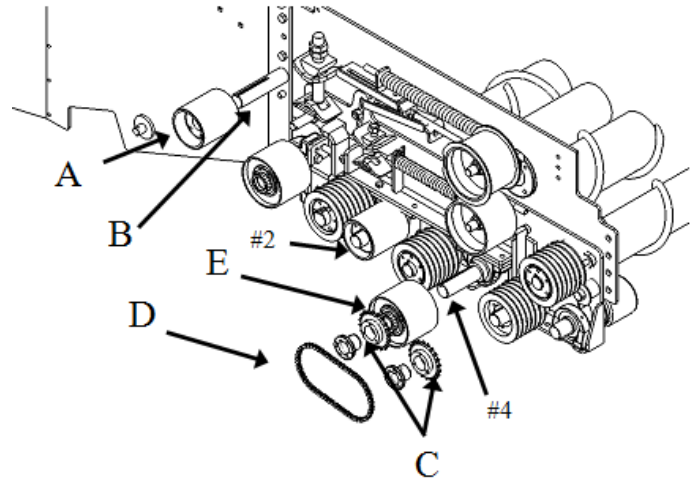


Figure 67: Installing Reverse Grabroll Kit (Pictured- 6 row)

7.22 Head Shaft Sprocket Dimensions

The distance between the head shaft sprockets, idler sprockets, and idler rollers is important. The schematics shown in Figure 68 are a good starting point for sprocket and roller placement.

IMPORTANT: Dimension (G) is the distance between the face of the sprocket and the walls of the elevator. This dimension must be equal on both sides of the shaft.

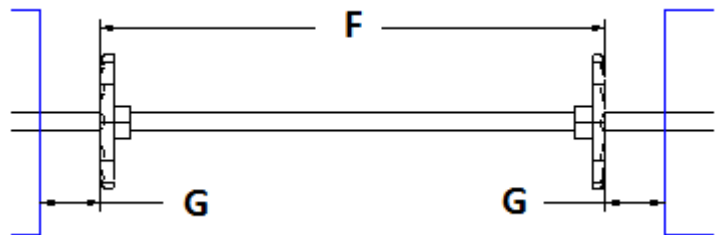


Figure 68: Sprocket and Roller Placement

Table 7

Chain Type	Sprocket Dimension (A)
42 in. (107 cm) Belted Chain	36.5 in. (92.7 cm)

7.23 Slip Clutches

Harvesters are equipped with fiber pad slip clutches on the paddle shaft and apron shaft. Some may also have slip clutches on the rear scrub drive. These slip clutches prevent failure of rotating components in the event they stop rotating. All slip clutches are set at the factory, and no field adjustments are necessary.

IMPORTANT: Do not use any type of oil on slip clutches.

Tubes of preset length are housed inside the slip clutch springs. These tubes prevent over-tightening of the slip clutch. Do not remove the preset tubes and retighten the slip clutch.



Figure 69: Slip Clutch

7.24 Rear Scrub

7.24.1 Inside Roller Location

Harvesters equipped with a scrub come standard with a dynamic chain management. This hydraulically controlled tension system maintains constant belt tension across a range of field conditions. This system pressure is set to 250 psi from the factory. Do not adjust this setting.

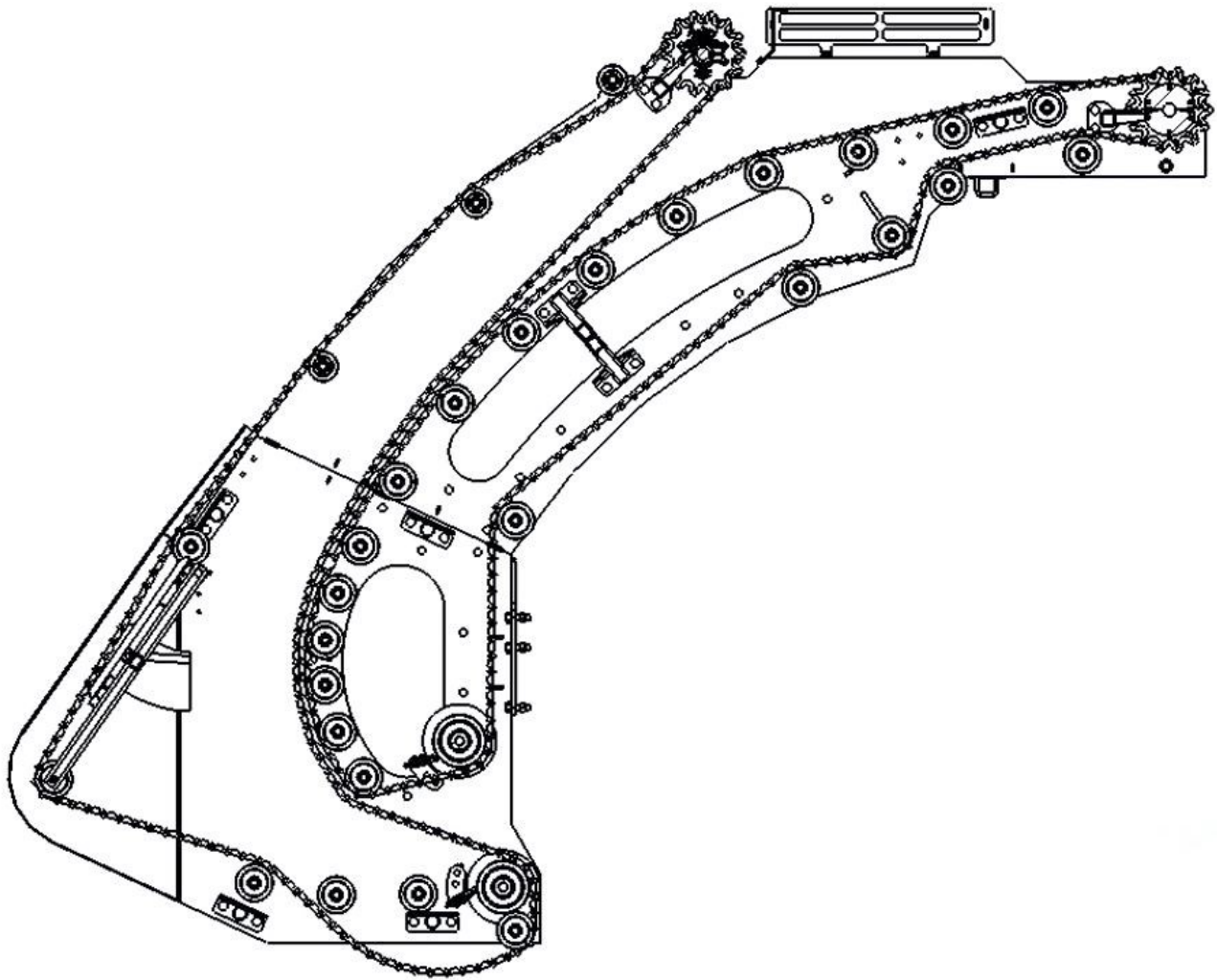


Figure 70: Rear Scrub shown with Scrub Chain, Rollers, and Head Shafts

7.24.2 Outside Scrub Chain Tension:

The outside scrub chain tension is adjustable to increase or decrease the capacity for beets. To increase the capacity of the scrub chain, head shaft (Detail A), shown in Figure 74, must be moved back to provide more slack in the chain. To adjust the head shaft location:



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Remove pressure of the belt on the head shaft sprockets.
3. Remove nuts (H) and lock washers (I). Pull out bolt (J) and washers (K).
4. Slide bearing (L) to the appropriate holes and insert washers (K) and bolts (J).

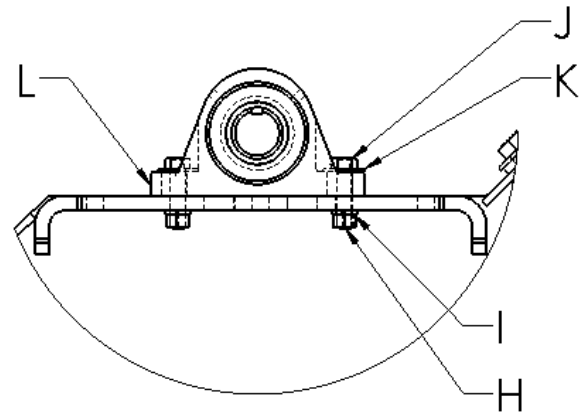


Figure 71: Adjusting Head Shaft Location

NOTE: Sliding the bearing towards the rear increases capacity and towards the front decreases capacity.

5. Loosely tighten nuts (H) and lock washers (I).
6. Move to the other side of the scrub, and repeat steps 2-4. Make sure the shaft is aligned. Fully tighten nuts (H).
7. Return to the original side, and fully tighten nuts (H).
8. Reapply pressure of the belt and check chains for proper alignment.

7.25 Rear Wheel

NOTE: Rear wheel wear drive plates (M) should be rotated prior to wear in the wheel weldment.

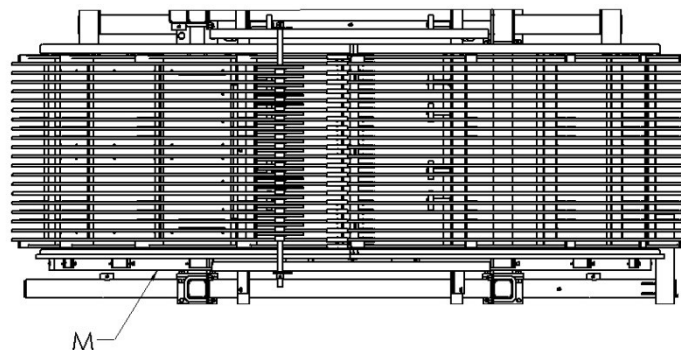


Figure 72: Rear Wheel Wear Drive Plates

7.25.1 Wheel Speed/ Conveyor Speed:

The wheel and conveyor speed flow controllers are shown in Figure 73.

To increase the speed of either component, move the switch in a manner such that the corresponding number increases. Likewise, decreasing the number will decrease the speed.



Figure 73: Flow Controllers

7.25.2 Wheel Drive Chain Tension:

To adjust the wheel drive chain tension:



1. Shift to park, disengage the PTO, lower the machine to the ground, relieve hydraulic pressure, stop the engine, remove the ignition key, and wait for all moving parts to stop before dismounting.
2. Tighten nut (A) until at desired chain tension.

If the spring is fully compressed and more chain tension is required:

3. Loosen nut (A) until the spring is not under compression.
4. Remove nut (B) and the bolt. Line up the second hole from the top with the arm linkage. Replace the bolt, and tighten nut (B).
5. Tighten nut (A) until at desired chain tension.

For more tension, follow steps 3-5 for the third hole.

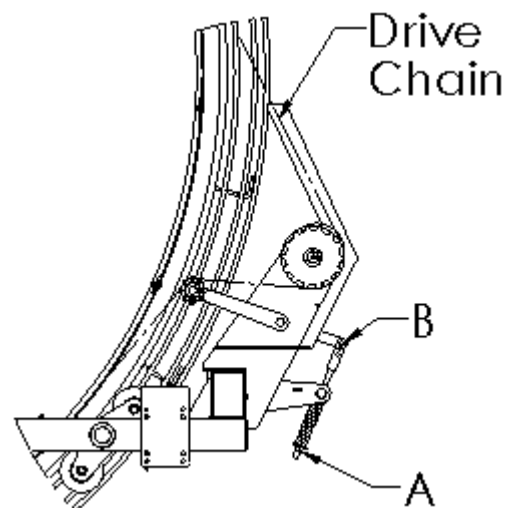


Figure 74: Wheel Drive Chain Tension Adjustment

8.0 TRANSPORTATION

8.1 Warning Lights

! **CAUTION:** Prevent collisions between other road users, slow moving tractors with attachments or towed equipment, and self-propelled machines on public roads. Frequently check for traffic from the rear, especially in turns, and use turn signal lights or hand signals.

Use headlights, flashing warning lights, and turn signals day and night. Follow local regulations for equipment and marking. Keep lighting and marking visible and in good working order. Replace or re-pair lighting and marking that has been damaged or lost.

8.2 Preparing for Transport

1. Run the machine until it is clear of beets and the tank is empty.
2. Clean all soil and debris off the machine.
3. Lower the boom.
4. Raise the machine out of the ground.
5. Make sure all safety decals and lights are clean and visible and all tail lights and turn signals function properly.

! **CAUTION:** Always use warning lights when transporting. Braking distance is greatly increased when towing a harvester.

NOTE: See section 3.0 For maximum transport speeds.

8.3 Wheel Option

NOTE: Axle cylinders must be extended during transport to gain clearance for the drive wheel.

! **CAUTION:** Be aware of overhead obstructions.



Figure 75: Lowered Boom

9.0 CLEANING

Cleaning is an important part of harvester maintenance. This section illustrates a few points where mud will routinely build up and need to be cleaned.

9.1 Row Finder

Row finder wands (A) and springs (B) must be cleaned routinely in order for the row finder to correctly locate beets.

Also, clean the area around the hydraulic valve spool and all other moving components to prevent seal failure.



Figure 76: Row Finder Cleaning

9.2 Lifter Struts and Paddles

Lifter struts and paddles typically require the most frequent cleanings. Any mud buildup around the lifter struts and paddles must be periodically removed for optimum performance and to prolong machine life.

IMPORTANT: If left unclean, mud buildup in these areas may lead to paddle shaft failure, slip clutch failure, excessive paddle wear, lifter strut seal damage, and/or lifter strut bearing failure.



Figure 77: Lifter Strut and Paddle Cleaning

9.3 Grabrolls

Mud buildup on grabrolls can typically be eliminated by proper drive sheave selection. If increasing grabroll RPM does not eliminate mud buildup, clean the grabrolls periodically until conditions improve.



Figure 78: Grabroll Cleaning

9.4 Apron Shafts

If mud buildup occurs under or between the apron chains, mud must be removed from the apron shafts.



Figure 79: Apron Shaft Cleaning

9.5 Rear Scrub

The interior of the inside chain on the rear scrub may build up with mud balls or beets. This area should be checked frequently and emptied if buildup occurs. The areas around the bogie wheels and frame cross members must also be kept clean. If left unclean, mud balls may cause belted chain to jump off the sprockets.



Figure 80: Rear Scrub Cleaning

9.6 Beet Tank

The elevator, boom structure, bogie wheels, slides, and frame members should be cleaned frequently to prevent soil buildup.

Excess soil in the beet tank causes undue strain on the elevator's hydraulic motor.

NOTE: Open the tank to clean.



Figure 81: Beet Tank with Open Tailgate

10.0 STORAGE

10.1 End of Season

1. Thoroughly clean the harvester inside and out. Debris and dirt will draw moisture and cause rust.
2. Inspect the harvester for any damaged or worn components; repair or replace as required.
3. Loosen or remove the drive belt. This will prolong the life of the belt.
4. Touch up paint on all parts from which paint has been worn to prevent rusting.
5. Clean all chains by washing with diesel fuel. Dry well and lubricate (see Lubrication and Maintenance, section 11.0).
6. Lower the boom.
7. Move the harvester to a level, dry, and clean area.
8. Put blocking material under the lifter wheels to prevent sinking and under the rear struts to take load off the tires. Do not deflate the tires. If exposed to the elements, put covers over tires to protect them from light, grease, and oil.

10.2 Beginning of Season

1. Attach the harvester to the tractor (see section 5.0).
2. Remove all support blocks from the lifter struts and rear struts.
3. Lubricate the entire machine (see Lubrication and Maintenance, section 11.0). This will force any collected moisture out of the bearings. Replace the gearbox oil and hydraulic oil (see Lubrication and Maintenance, section 11.0).
4. Reinstall the drive belt and verify all pulleys, idlers, and slip clutches are functioning properly.
5. Run the harvester to ensure proper function.
6. Tighten all loose components including guards and shields.
7. Review the operator's manual prior to operation.

IMPORTANT: All components that are damaged or worn must be repaired or replaced before operating the harvester (see parts book for part numbers).

11.0 LUBRICATION AND MAINTENANCE

11.1 General Maintenance Information

Perform each lubrication and service illustrated in this section at the beginning and end of each season.

IMPORTANT: The period for recommended lubrication and maintenance is based on normal conditions. Severe or unusual conditions may require more frequent lubrication or oil changes.

IMPORTANT: The items listed separately from the lubrication chart and the servicing interval pages are of extra importance. These items must be well maintained and checked routinely to maximize their lifespan.

11.1.1 Grease: SAE multipurpose high temperature/ extreme pressure grease with less than 1% molybdenum disulfide grease should be used.

Clean grease fittings before using a grease gun. Replace any lost or broken fittings immediately. If a new fitting fails to take grease, remove it and check for failure of adjoining parts.

11.2 U Joints

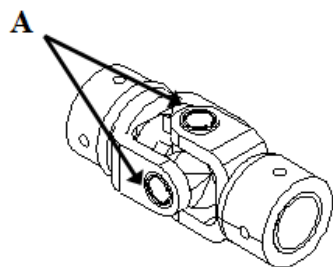


Figure 82: Needle Bearings

IMPORTANT: On needle bearings (A), use of grease with more than 1% molybdenum disulfide content may lead to premature U joint failure.

11.3 Hydraulic Oil Tank Level

The hydraulic oil tank should be filled so that 2 in. (5.1 cm) of oil shows above the low level line.

NOTE: Check the oil level every 10 hours.

OIL SPECIFICATIONS
SAE 10 W [ISO 32]
37 Gallons [140 Liters]

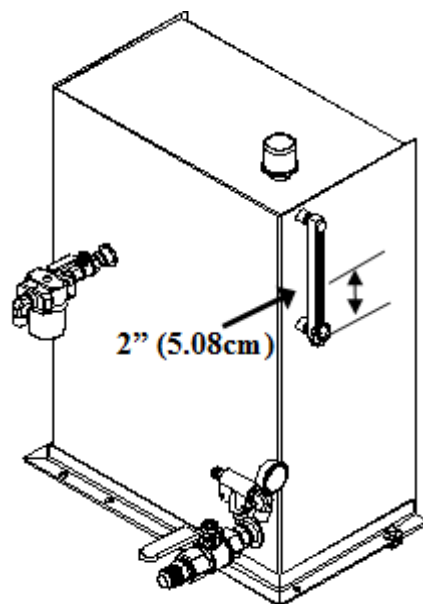


Figure 83: Hydraulic Oil Tank Level

11.4 Roller Chain

Apply the proper amount of oil to roller chain (A) to prevent the bearings from becoming dry.

IMPORTANT: Excess oil applied to the roller chain may contaminate slip clutch (B).

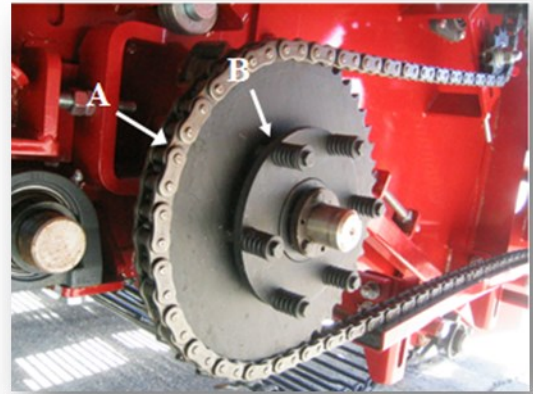


Figure 84: Roller Chain and Slip Clutch

11.5 Drive Belt

Check drive belts for wear every 10 hours.

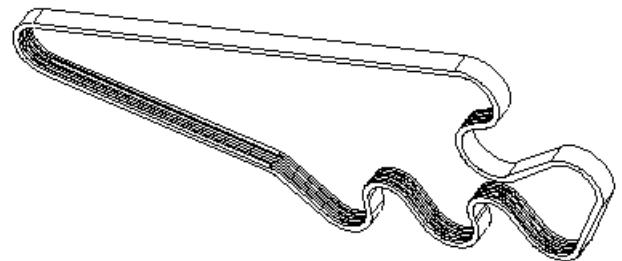


Figure 85: Drive Belt

11.6 Lifter Strut Hubs

Lifter strut hubs (A) need to be repacked with grease, have seals checked, and spindle nut re-torqued every 400 acres or sooner in sever conditions.

11.6.1 Torqueing Spindle Nut:

1. Ensure the seal and bearings are seated properly before tightening the spindle nut.
2. Torque the spindle nut to 200 ft-lb (271.2 N·m) while continuously rotating hub (A). At this point, the hub should be difficult to rotate.
3. Loosen the spindle nut one full turn or until it's loose.
4. Torque the spindle nut to 50 ft-lb (67.8 N·m) while continuously rotating the lifter wheel hub.
5. Back off the spindle nut $\frac{1}{6}$ of a turn or just enough to install the cotter pin in the spindle.

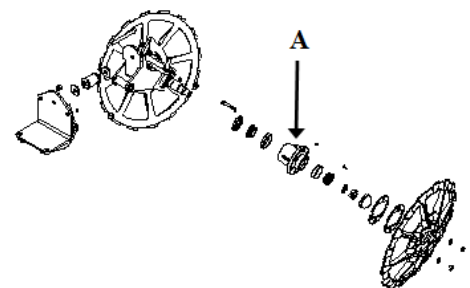


Figure 86: Hub

11.7 Gearbox Oil Level

Gearbox oil levels should be checked routinely and filled to line (A) shown in Figure 87.

Side plugs (B) can be found on all gearboxes and can be used to measure the correct fill level.

When gearboxes are filled with the proper amount of oil, the level should be just below the threads of side plug (B). Excess oil can be drained from the gearbox using side plug (B).

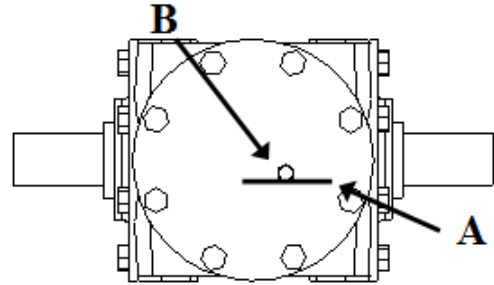


Figure 87: Gearbox Breather

11.8 Breather Cleaning

The breather must be able to vent atmospheric conditions during heating and cooling cycles of operation. If it cannot vent, oil will seep out seals and run low. Prolonged operation with low oil levels will damage the internal components. To clean the breather:

1. Remove breather (A).
2. Stop up the breather opening using a plastic plug or a clean rag to prevent contaminants from entering the gearbox.
3. Soak the breather in solvent for one hour.
4. Use a pointed instrument or wire to remove any residue from breather passages.
5. Blow out the breather with high pressure air.
6. Blow through the breather to ensure the passages are clear.
7. Reinstall and tighten breather (A) in the gearbox.

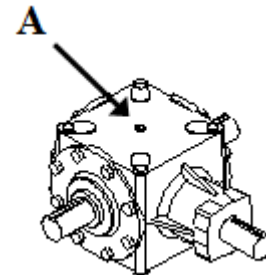


Figure 88: Gearbox Oil Level

11.9 Slip Clutch Maintenance

Prior to use each year, slip clutches should be tested to ensure they are functioning properly. To test slip clutches:

1. Loosen the springs by loosening 6 spring bolts (A).
2. Rotate sprocket (B) 1 to 2 revolutions to ensure proper fiber pad slippage.
3. Retighten bolts (A) to original torque.

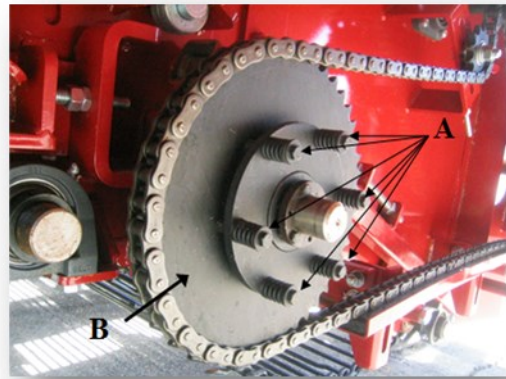


Figure 89: Testing Slip Clutch

Fiber pads within the slip clutch must be replaced once excessive slippage occurs.

IMPORTANT: Do not contaminate slip clutches with oil. This may cause slippage and lead to premature fiber disc replacement.

11.10 Hook Rod Chains

Hook rod chain, such as apron chain, is a high wear item. Hook rod chains should be replaced when the chain is worn 40% through at the joints.

40% = approximately $\frac{3}{10}$ in. (.8 cm) remaining in $\frac{1}{2}$ in. (1.3 cm) chain.

NOTE: Sprockets should typically be replaced when replacing chain.

NOTE: By the time apron chain has experienced 40% wear, approximately 10 links will have been removed from each section.

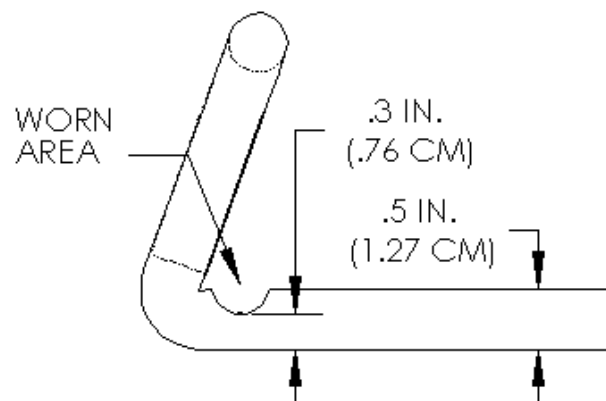


Figure 90: Hook Rod Chain Wear

11.11 Servicing Intervals

Before 1st Use:

1. Grease hitch, drivelines, row finder, U joints, and PTO driveline assembly
2. Check all gearbox oil levels.
3. Do not grease ball bearings.

5 Hours:

1. Grease driveline.

12 Hours:

1. Grease row finder, hitch assembly, lifter strut rod (when equipped with rock struts), belt idler pivot hub, hitch assembly, sealed bearings, and rear strut.
2. Oil all roller chains using a hand held oil can to control the amount and position of oil placement.
3. Check tightness of the following: lug bolts on rims, lifter strut mounting bolts, hubs on sheaves and sprockets, rear struts mounting bolts, bearing mount on grabrolls, splice bolts on all belted chains, drive sprockets for belted and hook chain.
4. Service apron chain. Check tension, and remove links if necessary.
5. Check belted chain splices.
6. Check for drive belt tension and wear; check idlers for proper tension and alignment. Adjust as required.
7. Check roller chain tension and wear; check sprockets and idlers for proper tension and alignment. Adjust as required.

40 Hours:

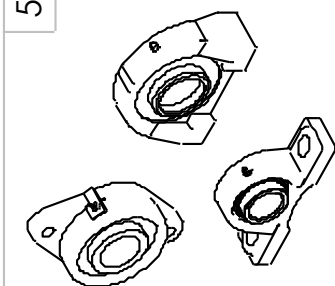
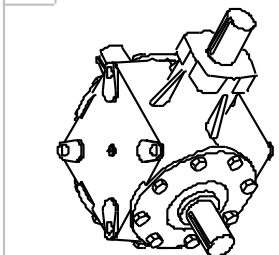
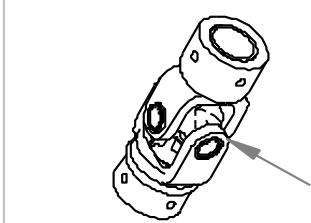
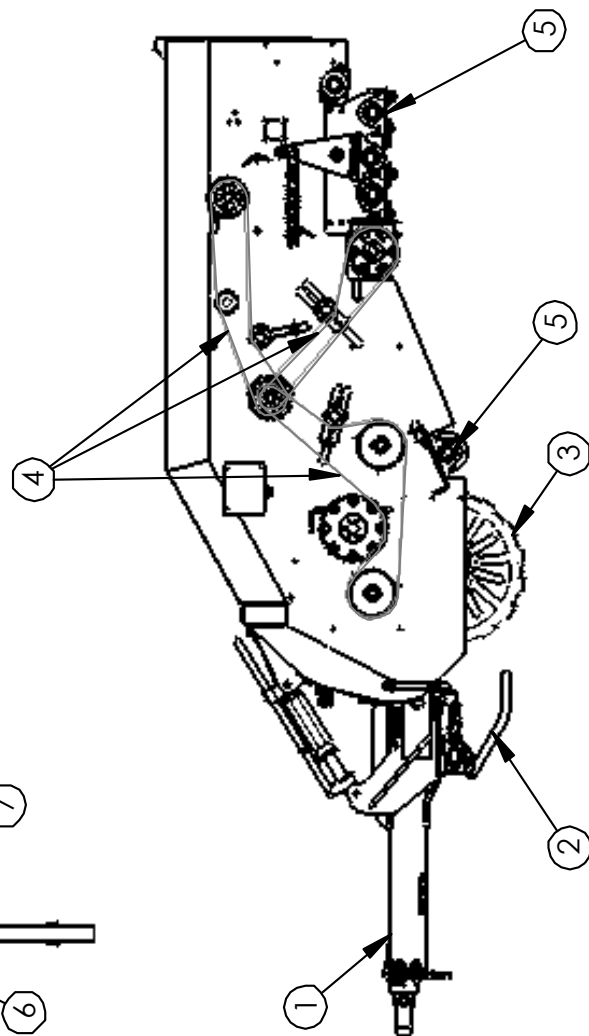
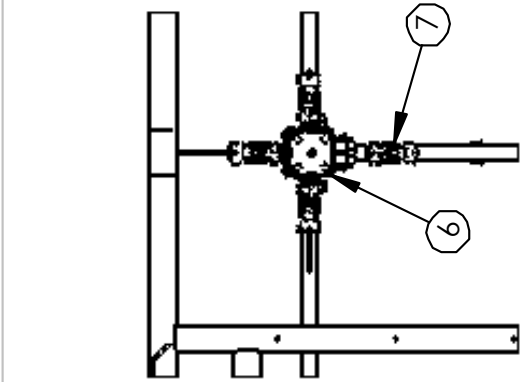
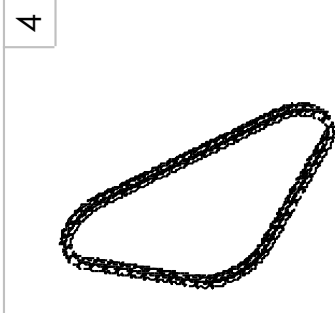
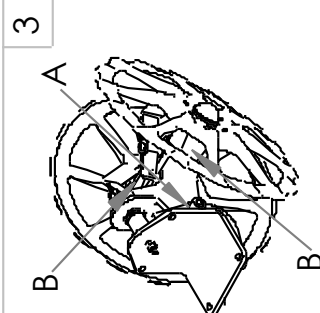
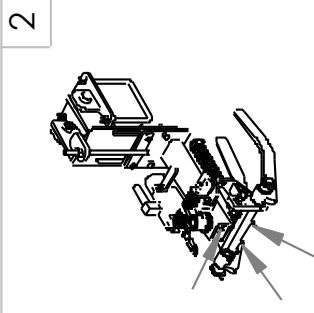
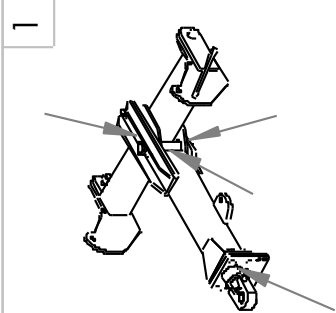
1. Lubricate the elevator hinge and all U joints
2. Lubricate the hydraulic cylinder pivot points.
3. Check oil level in gearboxes. Fill to proper level. Check more often if leaks are noticed.
4. Check wear on elevator plastic slides, idler wheel bearings, and bogey wheel bearings, and replace as necessary.

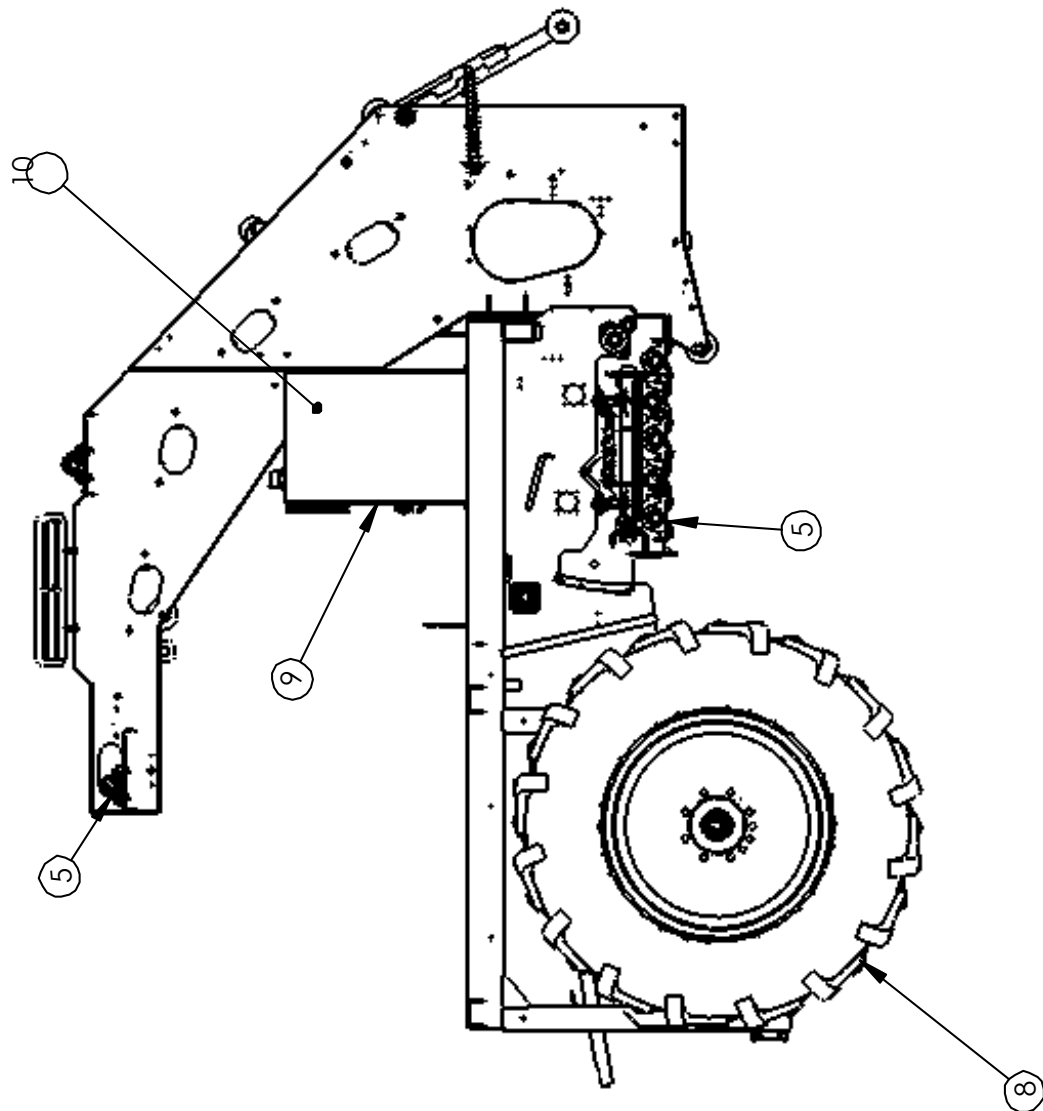
250 Hours or Annually:

1. Repack rear strut hubs, and lifter wheel hubs.
2. Change hydraulic oil and replace filter.
3. Change oil in gearboxes, rinse gearbox when oil is replaced.
4. Clean gearbox breathers.

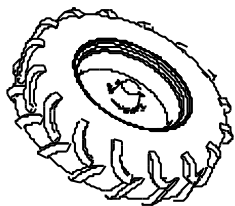
11.12 Lubrication Chart

Ref #	Description	Lubrication Type	Frequency	Quantity	Number of Instances
1	Hitch Assembly	Multi-Purpose Grease	12 Hours	3-5 pumps	4
2	Rowfinder	Multi-Purpose Grease	12 Hours	1-2 pumps	3
3a	Lifter Strut Rod-	Multi-Purpose Grease	12 Hours	2-3 pumps	2
3b	Lifter Strut- Hub	Multi-Purpose Grease	40 Hours	1-2 pumps	2
4	Roller Chain	SAE 20 (20 to 40°F)	12 Hours	As required	8
5	Sealed Ball Bear-	Multi-Purpose Grease	12 Hours	1-2 pumps	Multiple
6	Front Gearbox	EP 80W90 Oil	250 Hours/ Annually	5 Qt.	1
	Rear Gearbox	EP 80W90 Oil	250 Hours/ Annually	3 Qt.	1
7	U-Joint	Multi-Purpose Grease	40 Hours	2-3 pumps	5
8	Rear Strut	Multi-Purpose Grease	250 Hours	1-2 pumps	2
9	Hydraulic Tank	ISO 32 Equivalent [SAE low]	250 Hours/ Annually	37 Gal [140 L]	1
10	Oil Filter	ZINGA #AE25	250 Hours/ Annually	1 filter	1

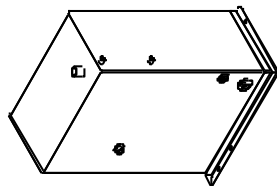




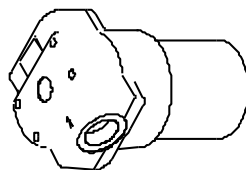
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10



11.13 PTO Driveline Servicing

The first lubrication interval should be 16 to 24 hours of operation after initial start-up. Then follow the schedule outlined in Table 9.

NOTE: A 1% Molybdenum disulfide grease should be used for the grease points listed below.

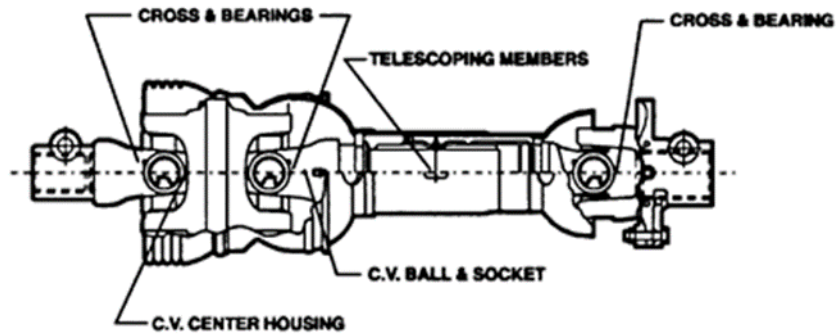


Figure 91: PTO Shaft

Table 9: PTO Driveline Servicing

Description	Frequency	Quantity	Instances
Cross and bearings*	8 hours	2-3 pump	3
Telescoping members	8 hours	8-10 pumps	1
CV ball and socket*	8 hours	2 pumps	1
CV center housing*	24 hours	2 pumps	1

*Constant angle applications must have a lube interval of 4 hours.

NOTE: Replacement parts are not lubricated. They must be lubricated at the same time of assembly. Use amounts listed above per location. Then, follow the above recommendations.

12.0 TROUBLESHOOTING

PROBLEM	CAUSE	SOLUTION
Lifter wheels slicing beets.	Lifter wheels not adjusting to row spacing.	Set lifter strut spacing to same as beet rows.
	Row finder wands clogged, or row finder is not adjusted or working properly.	Adjust or clean rowfinder (see section 7.2).
	Machine is not level.	Level machine (see section 7.1).
	Irregular planting.	Align harvester with rows using manual override.
	Paddle shaft too slow.	Increase PTO speed or hydraulic speed.
Loss of beets in lifter wheels.	Pinch point is too wide.	Remove wheel spacers to obtain narrower pinch point (see section 7.4).
	Losing beets between wheel spokes.	Install wheel fillers.
	Ground speed too slow.	For proper speed see section 6.2.
	Tractor operating under 1000 RPM PTO speed.	Increase tractor throttle so PTO rotates at 1000 RPM.
	Lifter wheels digging too shallow.	Lower machine.
	Paddle shaft too slow.	Increase PTO speed or hydraulic speed.
Loss of beets through grabrolls.	Rollers too far apart.	Move rollers closer together, or tighten rock spring (see section 7.15).
	Dirt sticking to rollers.	Install larger drive sheave to speed up grabrolls (see section 7.14).
	Angle of grabroll bed adjusted incorrectly.	Raise front of cleaning bed to increase flow of beets through grabrolls (see section 7.19).

PROBLEM	CAUSE	SOLUTION
Excessive debris/mud being loaded into machine.	<p>Poor defoliation job.</p> <p>Digging too deep.</p> <p>Unnecessary use of wheel fillers.</p> <p>Pinch point is too wide.</p> <p>Paddle shaft too slow.</p>	<p>Run defoliator over field again to eliminate excess debris.</p> <p>Make sure defoliator is adjusted properly.</p> <p>Raise machine to dig shallower.</p> <p>Remove Wheel fillers.</p> <p>Adjust pinch point width (see section 7.4)</p> <p>Increase PTO speed or hydraulic speed.</p>
Grabrolls backing up with beets.	<p>Bed angle too steep.</p> <p>Grabrolls moving too slow.</p> <p>Smooth rolls too low.</p> <p>Front grabroll flap in down position.</p> <p>Traveling too fast while harvesting.</p> <p>Outside scrub chain too tight.</p>	<p>Adjust grabroll bed angle (see section 7.19)</p> <p>Speed up grabrolls by installing a larger drive sheave (see section 7.14).</p> <p>Raise smooth grabrolls (see section 7.17).</p> <p>Move into up position (see section 7.13).</p> <p>Slow down.</p> <p>Reposition head shaft (see section 7.25.2).</p>
Beets not coming out of lifter wheels.	<p>Paddle shaft not adjusted properly.</p> <p>Rubber paddles worn severely.</p> <p>Beets aren't being lifted to paddles.</p> <p>Digging too deep.</p>	<p>Lower paddle shaft (see "Paddle Shaft Position" in Adjustments").</p> <p>Replace rubber paddles.</p> <p>Increase ground speed (see "Operating Speed" in Operating the Harvester).</p> <p>Raise machine to prevent excessive amounts of material from being loaded.</p>
Grabrolls clogging with beets before scrub is full.	Rear scrub chain too tight.	Adjust tension by moving rear scrub rollers (see section 7.25).

PROBLEM	CAUSE	SOLUTION
Lifter wheels plugging.	Digging too deep.	Raise machine.
	Paddles not keeping wheel rim clean.	Adjust the paddles outward and/or down (see section 7.8).
	Scrapers not close enough to wheel.	Adjust scrapers with adjusting bolts (see section 7.6).
	Rocks clutching or stopping lifter wheel rotation.	Change position of pinch point (see section 7.3).
	Excessive mud.	Clean machine.
Beets coming out front of machine.	Paddles too wide.	Adjust inward (see section 7.8).
	paddles not reaching deep enough into lifter wheels.	Lower paddle shaft (see section 7.8).
	Apron chain tension too loose.	Adjust chain tension (see section 7.10)
Excessive soil being loaded into machine.	Digging too deep.	Raise machine.
	Ground speed too fast.	Reduce ground speed.
	Incorrect pinch point position.	Roll pinch point forward (see section 7.3)
	Wheel fillers are installed.	Remove wheel fillers (see section 7.5)
	Pinch point is too wide.	Remove lifter wheels spacers (see section 7.4)
Soil build-up on grabrolls.	Loading excessive soil.	Refer to problem listed above.
	Grabrolls moving too slow.	Speed up cleaning rolls with larger drive sheave (see section 7.14)
	Soil conditions (clay, mud, temperature).	Clean more frequently.

PROBLEM	CAUSE	SOLUTION
Tires built up with soil.	Soil conditions.	Cclean rear struts frequently (see section 9) Lower tire pressure (see section 3.1)
Scrapers building up with mud.	Scrapers too far from lifter wheels.	Adjust outward to wheels (see section 7.6).
	Soil conditions.	Move paddles out close to lifter wheels (see section 7.7).
Mud building up on lifter.	Paddles not close enough to lifter wheels.	Move paddles out closer to lifter wheels (see section 7.7).
	Digging too deep.	Raise machine.
	Soil Condidions.	Clean lifter struts frequesntly (see section 9.0)
	Scrappers adjusted incorrectly.	Adjust toward lifter wheels (see section 7.6).
Breaking beets.	Digging too shallow.	Lower machine.
	Small beets or dry conditions.	Install reverse #4 grabroll kit.
	Grabrolls moving too fast.	Install smaller drive sheave (see section 7.14)
	Pinch point too marrow.	Add wheel spacers (see section 7.4).
	Tractor tires running over beets.	Adjust tractor tires properly (see section 7.1.2).
	Grabrolls opeded too far.	Close up grabrolls (see section 7.12 for front and 7.18 for back).

13.0 Appendices

13.1 ISOBUS ADC Operation Introduction

Active Depth Control (ADC) is an electric over hydraulic control system that levels and maintains the harvester at a constant digging depth while harvesting based on a variety of field conditions. Using hydraulic oil supplied from the tractor, a valve bank on the harvester sends oil to hydraulic cylinder on the hitch and rear axle to raise and lower the harvester to allow it follow the ground evenly. To determine what should be considered level with the ground the harvester has two mechanical wands at the front of the machine that ride on the ground. Using sensors on these wands the electronic control unit (ECU) controls the valve bank to level the harvester.

This system is an ISOBUS platform. ISOBUS is an international communication that standardizes communications between tractors and implements. To control this system then, the operator will interface with it using any tractor's ISOBUS compatible virtual terminal (VT).

13.1.1 Terminology

For clarification purposes the following are some terminology descriptions that are used in this manual.

- **Select/Selecting:** There are many different VTs in the industry which come with different ways of performing actions. Most new VTs are touch screen so "Selecting" on a touch screen simply means to touch. Some VTs have physical buttons that correspond to things on the screen. "Selecting" would be pushing those physical buttons. Other VTs have a scrolling knob that allows the user to scroll the knob to highlight icons on the screen which can then be selected by a physical button or pressing on the knob.
- **Virtual Terminal:** The virtual terminal or VT is the physical screen that the user will interface with.
- **Softkeys:** Softkeys are a set of icons that are used to perform actions on the VT. These icons are usually off to one side of the screen and come in a list form. Different VTs will display different amounts of softkeys at one time and almost all will require the user to page through to access all available icons.
- **Page:** A page is larger portion of the screen that displays the information about the system. Different pages will display different information and have different options for the user. For the definition purposes of this manual the VT will display two sections on the screen for use with the ADC system, the page and the softkeys. Figure 92 shows an example of the screen. Note, your screen may different in appearance.

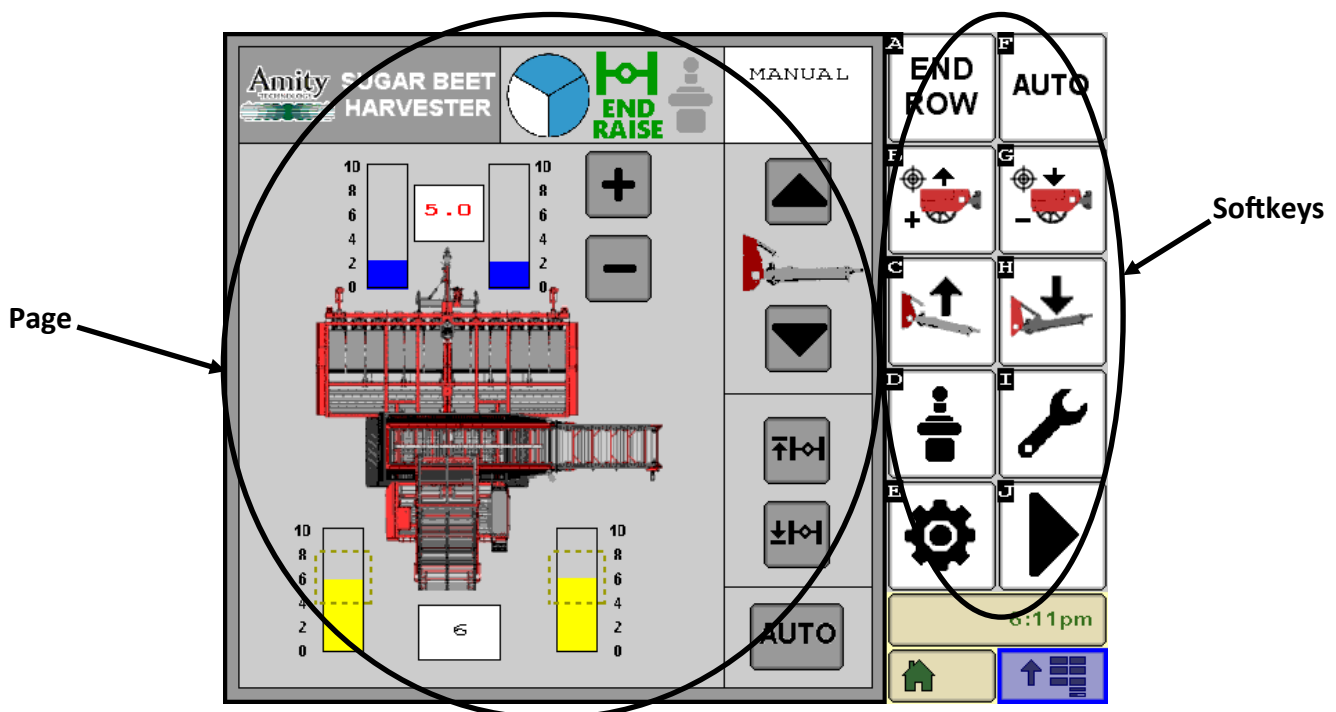


Figure 92—Screen Sections

13.1.2 Safety

As the operator you are responsible for the safe operation and maintenance of on the Active Depth Control on your Amity sugar beet harvester. You and anyone else, who will operate, maintain, or work around the harvester while in use should be familiar with the operation, maintenance, and safety information in this manual.

The most important safety device on this equipment is a safe operator. Any person who has not read and understood all the operation and safety instruction of not only the ADC system but the entire harvester is not qualified to operate this system.

NOTE!!!!


















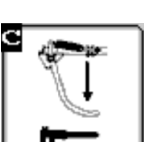
It is very important to understand that as an automated system they system will move the harvester with out direct input for the operator. Any time there is hydraulic oil supplied to the harvester ADC 's valve bank the harvester has the potential to move.

For the safe operation and maintenance of the ADC system follow these rules:

1. Read and understand this operator manual on how the system works, and what all the controls are and do.
2. Only supply hydraulic oil to the ADC valve when you are ready and intend to use the system. Make sure all person and objects are outside the danger zone of the harvester before supply oil. Shut of the oil supply any time the system will not be in use.
3. Note that anytime oil is supplied to the valve, any control used on the VT there is potential for the harvester to move.
4. Be on high alert when ever the system is in "Auto" mode. The harvester will automatically move based on feedback from the depth wands, not by the operator.
5. Deactivate the joystick anytime it is not in use to prevent any chance of unintentional operation by accidentally bumping it.
6. Before ever exiting the tractor, tun of the PTO, stop the flow of hydraulic oil to the harvester, and turn off the tractor.
7. Follow any and all other safety instruction through the harvesters operators manual.
8. "Auto" mode can not be activated with out the PTO running but all other functions will work.

13.1.3 Softkey Definition

Below are sort definitions of all the different softkeys used in the system.

	<u>Auto Toggle:</u> Enter and exits the system's "Auto" mode.		<u>Settings Screen:</u> Opens the setting screen.
	<u>End Row:</u> Enters the system's "End Row" mode.		<u>Diagnostic Screen:</u> Opens a diagnostic screen.
	<u>Raise Digging Depth:</u> Incrementally raises the digging depth target. Increments of 0.2"		<u>End Raise Toggle:</u> Turns on and off the rear axle end row raise feature.
	<u>Lower Digging Depth:</u> Incrementally lowers the digging depth target. Increments of 0.2"		<u>Active Alarm Screen:</u> Opens a screen that will display any and all active alarms.
	<u>Rear Axle Max Height:</u> Raises the rear axle all the way up.		<u>Joystick Toggle:</u> Activates and de-activates the use of the joystick.
	<u>Rear Axle Min Height:</u> Lowers the rear axle all the way down.		<u>Home Screen:</u> Opens the main screen.
	<u>Rear Axle Target Toggle:</u> Cycles through the rear axle target heights.		<u>Soft Key Pager:</u> Changes Soft key pages.
	<u>Raise Hitch:</u> Incrementally Raises the front of the harvester using the hitch.		<u>Sound Toggle (On):</u> Toggle the sound on and off. This icon indicates the sound is on.
	<u>Lower Hitch:</u> Incrementally lowers the front of the harvester using the hitch.		<u>Wand Calibration Success:</u> The wand calibration icon will change to this for 3 seconds with a successful calibration.
	<u>Wand Calibration:</u> Calibrates the wands.		

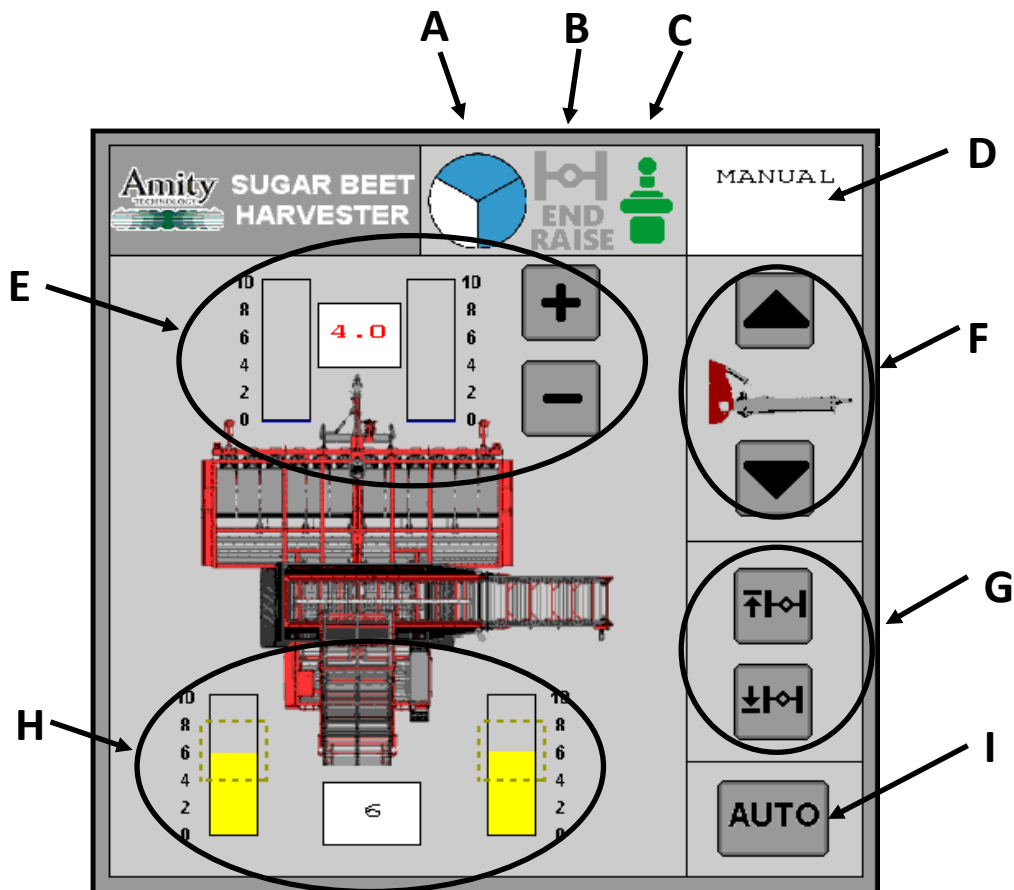


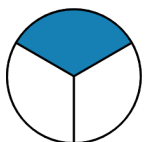
Figure 93—Main Page

13.1.4 Main Page

Figure 93 shows the main page of the ADC system. This will be the page that will display all the necessary information while harvesting. The follow are short description of what each part of the page means or represents.

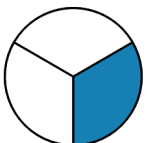
A - System Readiness Chart:

The system readiness chart is a pie chart that is made up of three section that represent criteria that must be met before the system can enter into “AUTO” mode. Below are the descriptions of each section of the pie.



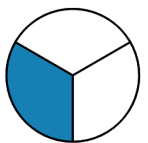
System Calibrated:

The top slice of the pie will be filled in if the wands have been calibrated.



System Error/Alarm Status:

The right slice of the pie will be filled in there are no active alarms.



PTO Status:

The left slice of the pie will be filled in if the PTO is running.



System Ready:

Once all the pies are filled in the Pie will change to a green circle with a check. This check means that all the requirements for entering into “AUTO” mode have been met.

B - End Raise Active/Inactive Icon:

The End Raise function is where the rear axle will raise all the way up when “END ROW” mode is entered. This function can be toggled on and off use a softkey (Figure 94). On the main page in the top right corner there is a End Raise icon that will change colors depending upon if the function is activated. The icon will be gray if the function is not active (Figure 95). The icon will be green if the function is active (Figure 96).



Figure 94—Toggle on/off Softkey



Figure 95—Function Inactive Icon



Figure 96—Function Active Icon

C - Joystick Active/Inactive Icon:

In order for the joystick to be used it must first be activated. To activate the joystick there is a softkey to toggle it on and off (Figure 97). On the main page in the top right corner there is a Joystick icon that will change colors depending on if it is active. The icon will be gray if the joystick is not active (Figure 98). The icon will be green if the joystick is active (Figure 99).



Figure 97—Toggle on/off Softkey



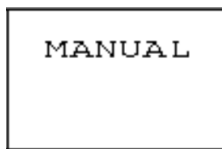
Figure 98—Joystick Inactive Icon



Figure 99—Joystick Active Icon

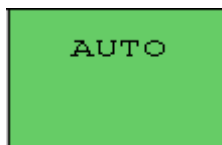
D - System Mode:

In the upper right Corner of the main page there is a current mode box that displays what mode the system is currently in. Below is a description of the modes.



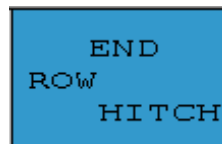
Manual Mode:

Manual mode is the natural state of the system. The system will not perform any action until input is received from the user.



Auto Mode:

Auto mode is the harvesting mode that when entered the system will try to reach the target depth and level the machine side to side. Once entered into this mode the system completely takes control of the hitch and rear axle cylinders and will move them based on input from the wands.



End Row Hitch Mode:

End Row Mode is a function that raises the harvester up and all the way out of the ground. When activated it raises the hitch to the end of its stroke. If the End Raise feature is active the rear axle cylinders will also raise all the way up. Used when turning the machine on headlands.

E - Target Depth and Wand Position Graph:

The Target Depth is the depth that system actively tries to make the lifter wheels dig into the ground. This number is displayed on the main screen between the two blue wand position bar graphs. It is important to note that this number does not represent the exact number of inches the lifter wheels are digging into the ground. While physically adjusting the height of the wands on the machine can make this number very close to that of the inches into the ground, this number is meant to just be a scaled reference number. Upon initially use, and periodically through out harvest, the actual depth of the lifter wheels should be looked at in a dug row to verify a satisfactory depth.

The target depth can be changed in a few different ways. It can be changed by selecting the plus and minus icons to the right of the bar graphs. This will change the depth in increments of 0.2. In certain configurations of the joystick, the joystick can be used to change the depth. See joystick section for more information. Again this will change the depth in increments of 0.2. There are also two soft keys that will raise and lower the depth in increments of 0.2 (Figure 101 and 102). The last way to change the target depth is by directly selection the target depth number which will cause a pop up key pad to appear and the a number can be manually entered in (Figure103). The depth can also be changed from the setting screen as well.

On either side of the target depth number is a bar graph that shows the instantaneous reading from the wands on the front of the machine. While harvesting these bars will move up and down with the wands as they travel over the ground. While there will be lots of movement and spikes you want to see that bars be close to you target depth show that the system is working correction and always working to achieve that target depth.

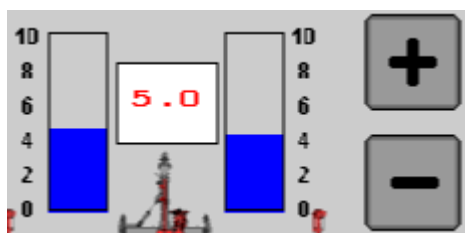


Figure 100—Target Depth & Wand Position



Figure 101—
Raise Target
Depth



Figure 102—
Lower Target
Depth

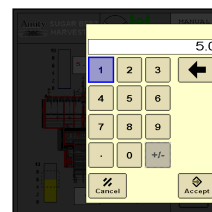


Figure 103—Pop Up Key Pad

F - Hitch Raise and Lower:

The hitch can be manually raised and lowed to adjust the height of the front of the harvester. By raising the hitch the harvester is raised. The are number of ways to raise the hitch. On the main screen there is a picture of the hitch with an up and down arrow that can be used to raise or lower the hitch (Figure 104). There are also two soft keys that will do the same thing. The last way is to configure the joystick to allow it to raise and lower the hitch, see joystick section.

In all options, the raise and lower hitch function controls the movement incrementally. Each press or selection moves the hitch for a certain amount of time. The amount of time is PTO dependent. If the PTO is not running the hitch will move for a longer period of time, or further, then if the PTO is running. If the PTO is NOT running the hitch will move for 4 sec. and if the PTO is running the hitch will move for 0.3 sec.

While in Auto mode if the raise hitch function is held for 3 seconds the systems will enter into an End Row function. Raising or lowering the hitch while in “AUTO” mode will cause the system to exit “AUTO” and enter “Manual” mode.

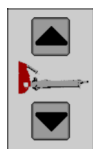


Figure 104—Hitch Raise and Lower



Figure 105—Raise Hitch Softkey



Figure 106—Lower Hitch Softkey

G - Rear Axle Max and Min:

The rear axle can be manually raised all the way up or lowered all the way if desired. There are two icons on the main screen (Figure 107) that can be used to achieve this along with two soft keys (Figure 108 and 109). By selecting the max height icon or softkey the rear axle cylinders will extend to the max stroke of 10 inches. By selecting the min height icon the rear axle cylinders will retract all the way.

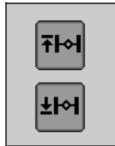


Figure 107—Max and Min



Figure 108—Min Axle Softkey

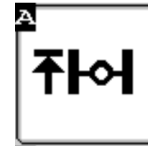


Figure 109—Max Axle Softkey

H - Axle Setpoint and Position:

The Axle Setpoint is the rear axle cylinder height that the system will target when in “AUTO” mode. This number represents the average stroke length of the left and right axle cylinders. When “AUTO” mode is entered the axle cylinders will move to meet the selected set point. To level the harvester the cylinders will move up and down while maintaining an average stroke distance of the setpoint. Meaning, if a difference of 2” is needed between the two cylinders to make the machine level, one cylinder will move up 1” from the set point and the other will move down 1” from the set point.

There are four different setpoints that can be selected, 2”, 4”, 6”, and 8”. The set point can be changed by selecting the setpoint which will cause a pop up list to appear and the set point can be selected (Figure 112). There is also a softkey that when pressed will cycle through the four set points (Figure 111). The set point can also be changed from the setting screen. The typical setting will be 2” for most harvesting. Selecting a higher number will increase the angle the beets are required to climb across the grab rolls and jump chain increasing the “cleaning” time the beets will see.

To either side of the setpoint number on the main page is a bar graph the show the instantaneous location of the cylinders within there stroke. Due to physical limitations in the axle, there can only ever be a maximum of a 4” difference in the cylinder strokes. On each bar graph is a dashed box that represents the limit of movement each cylinder will be able to move based on the current setpoint.



Figure 110—Axle Setpoint & Cylinder Graph

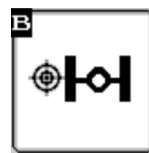


Figure 111—Setpoint Cycle Softkey

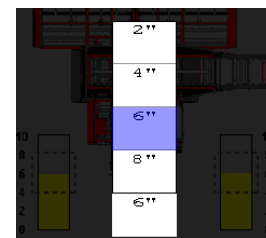


Figure 112—Setpoint Pop Up List

I - Auto Mode Icon:

Once all the requirements to enter “AUTO” mode have been met, see section 13.1.4, “A”. There are a few different ways to enter “AUTO” mode. On the main page in the bottom right there is a Auto icon that can be selected (Figure 113). There is also a soft key to enter “AUTO” mode (Figure 114). The final way is to use the joystick, see joystick section. All these options operate in an on/off capacity. One press will enter the system into “AUTO” and the next will exit the system out of “AUTO”.



Figure 113—Auto Toggle



Figure 114—Auto Toggle Soft Key

Amity SUGAR BEET HARVESTER		DIAGNOSTICS
System Voltage:	12.62	v
Left Wand Sensor Voltage:	2.72	v
Left Wand Depth:	0.00	in.
Right Wand Sensor Voltage:	2.75	v
Right Wand Depth:	0.02	in.
Left Axle Position Sensor Voltage:	1.85	v
Left Axle Height:	6.44	in.
Right Axle Position Sensor Voltage:	1.94	v
Right Axle Height:	6.24	in.
PTO Running:	NO	
Joystick Position:	center	
Auto Axle:	Enabled	
Software Version:	0.8.2200	
VT Info:	A000.1D00.0427.7823	

Figure 115—Diagnostics Page

13.1.5 Diagnostics Page

Figure 115 shows the Diagnostic page, which is a helpful tool if trouble shooting the system is required. This screen shows you live data from the ECU that can be used to determine if or where an issue might be. The follow are descriptions of each of the items displayed.

- **System Voltage:** The system voltage is the voltage being received from the tractor. It should be between 11 and 13.5 volts.
- **Wand Depth:** The wand depth is the depth that the system thinks the machine is currently at based on the wand position. When the machine is up in the air and the wands are not touching the ground these readings should be 0.00. If not the system needs to be calibrated, see section 13.1.8, "Calibration"..
- **Wand Sensor Voltage:** The wand voltage is the reading of the angle sensors on the wands in front of the machine. The volt age should be between 0.5 and 4.5 volts. As the wand is moved up and down the voltage should move between this range accordingly.
- **Axle Position Sensor Voltage:** The axle voltage is the reading from the rear axle cylinder sensors. The voltage should be between 0.25 and 4.75 volts. As the cylinders move up and down the voltage should move between this range accordingly.
- **Axle Height:** The axle height is the current stroke distance of the rear axle cylinders. The reading should be between 0 and 10 inches and should match the physical cylinder stroke distances.
- **PTO Running:** The PTO running is a simple "YES" or "NO" if the PTO is running. This is determined by a sensor at the front of the machine, just after the PTO shaft.

- **Joystick Position:** The joystick position is the current position of the joystick. This will display, “CENTER”, “NORTH”, “EAST”, “SOUTH”, “WEST” based upon which position the joystick is on. “Center” is the natural position of the joystick, straight out. “North” is shown as an arrow on the physical joystick.
- **Auto Axle:** Auto axle, displays an “ENABLED” or “DISABLED” based on if the END RAISE function is toggled on or off.
- **Software Version:** The software version is the current software version loaded onto the ECU.
- **VT Info:** VT Info, displays info about the physical screen’s hardware and software for trouble shooting and informational purposes.

13.1.6 Settings Page

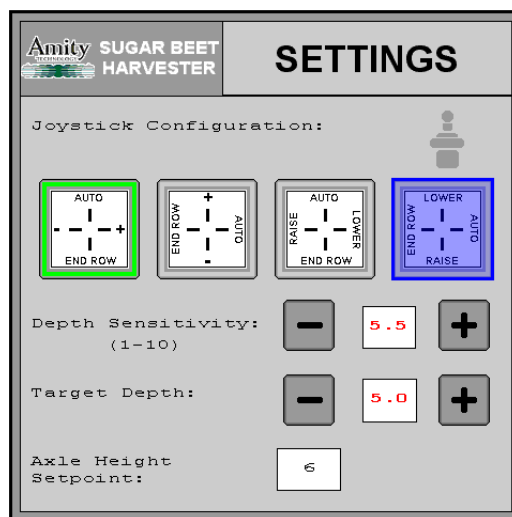


Figure 116 — Settings Page

Figure 116 shows the Setting Page, which displays and allows for changes to some setting for the system and are as follows:

- **Joystick Configuration:** The joystick has 4 different layout options. The joystick can perform 4 different functions by pushing it North, East, South, or West. North is designated by an arrow on the physical joystick and is considered the top function on this screen. To select a configuration press one of the options shown on the screen. The configuration will be boarded in green once selected to show which option is currently being used. The possible function that the joystick can perform are as follows:

1. **“AUTO”** - Toggles in and out of “Auto” mode.
2. **“END ROW”** - Enters the system in to “End Row” mode
3. **“+”** - Increase the target depth of the harvester. Increases the depth in increments of 0.2.
4. **“-”** - Decreases the target depth of the harvester. Decreases the depth in increments of 0.2.
5. **“LOWER”** - Lowers the front of the harvester using the hitch cylinders. The front will be incrementally lower with each movement of the joystick. The increment size is PTO dependent. See section 13.1.4, “F” for details. With the PTO running the movement will be small and with the PTO not running the movement will be greater. Using the “LOWER” or “RAISE” function will cause the system to exit out of Auto mode. It will raise or lower the machine and then enter in to manual mode .
6. **“RAISE”** - Raises the front of the harvester using the hitch cylinder. The front will be incrementally raised with each movement of the joystick. The increment size is PTO dependent. See 13.1.4, “F” for details. With the PTO running the movement will be small and with the PTO not running the movement will be greater.



Figure 117—Joystick Toggle Softkey



Figure 118—Joystick Inactive Icon



Figure 119—Joystick active Icon

In order for the joystick to be used it must be activated first. To active the joystick there is a softkey to toggle between activating and deactivating the joystick (Figure 117). When the joystick is active the icon on the screen will be colored green (Figure 119). When the joystick is inactive the icon will be gray (Figure 119). Changing the configuration will cause the joystick to become inactive until reactivated.

-Depth Sensitivity: The depth sensitivity controls the responsiveness of the machine when in “AUTO” mode. The higher the number the faster the system will react to the wand readings. The sensitivity can be set in the range from 1-10 in increments of 0.5. To change the value use the plus and minus icons on the sides of the current setting. By directly selecting the setting number a pop up key pad will appear and a number can be typed in manually.

Note: Oil temperature will affect the responsiveness of the system. It is recommend that the system only be used once the tractor and its oil has warmed up to normal operation temperature to reduce any fluctuation of the systems sensitivity .



Figure 120—Sensitivity Setting and Adjustment

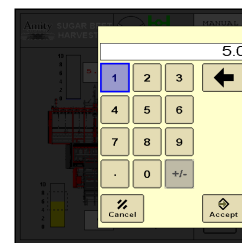


Figure 121—Pop Up Key Pad

- Target Depth:

The depth that the machine will try to achieve while in “AUTO” mode. The depth of the machine is determined by the wands in the front of the machine. To change the depth use the plus and minus buttons on the sides of the current setting. The plus and minus buttons will change the target depth in increments of 0.2. By directly selecting the setting number a pop up key pad will appear and a number can be typed in manually.



Figure 122—Target Depth Setting and Adjustment

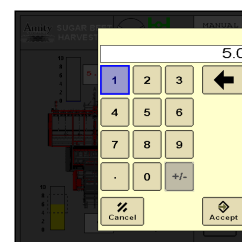


Figure 123—Pop Up Key Pad

- Axle Height Setpoint:

The Axle Setpoint is the rear axle cylinder height that the system will target when in “AUTO” mode. This number will be the average stroke distance between the left and right cylinders. When “AUTO” mode is entered the rear cylinders will move to meet the selected set point. To level the harvester the cylinders will move up and down while maintaining an average stroke distance of the setpoint. Meaning, if a difference of 2” is needed between the two cylinders to make the machine level, one cylinder will move up 1” from the set point and the other will move down 1” from the set point. There are 4 setpoint to chose form. (2”, 4”, 6”, and 8”) Select the current setting to make a list pop up for selecting a different

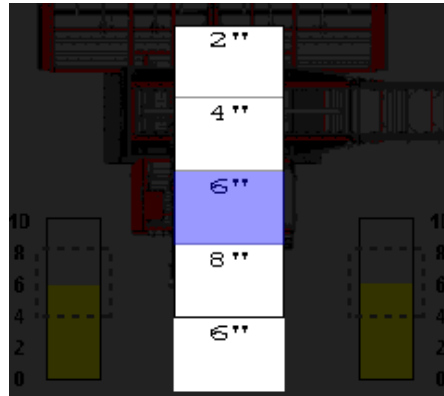


Figure 124—Axle Setpoint Pop Up List

- Sound Notifications:

If your VT is compatible with sound there is the option of having the screen beep when entering and exiting Auto mode. When entering “AUTO” the screen will produce one long beep. When exiting Auto mode the screen will produce two shorter beeps. While on the settings screen a soft key will appear that allows you to turn on or off this sound. The softkey itself will change in appearance to signify if the sound is on or off.



Figure 125—Sound On Softkey

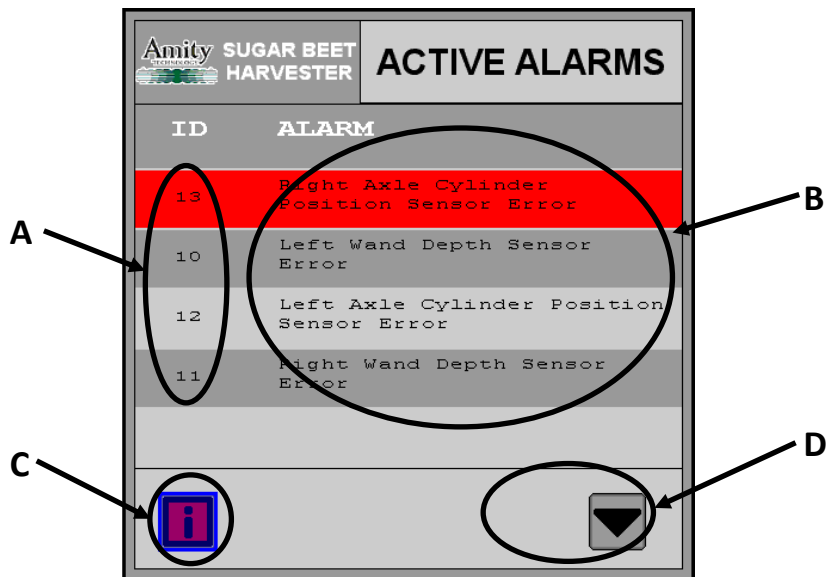


Figure 126—Active Alarms Page

13.1.7 Active Alarms Page

Figure 126 show the Active Alarm page. This page displays a list of any currently active alarms within the system. “AUTO” mode can not be entered while any alarms are active. This page can be accessed using the Alarm page softkey from any other page (Figure 127). Below are descriptions of the specific parts of the page.



Figure 127—Alarm Page Softkey

- **A—Alarm ID:** Each possible alarm has a specific alarm ID that allows for easy look up in the next couple of pages of this manual.
- **B—Alarm Title:** The alarm title is the name given to the alarm.
- **C—Information Icon:** By selection the Information Icon more information on the highlighted alarm is displayed. This pop up give a brief description of the alarm and possible causes. Figure 128 is an example of this pop up. To return to the list select the arrow in the bottom left corner.

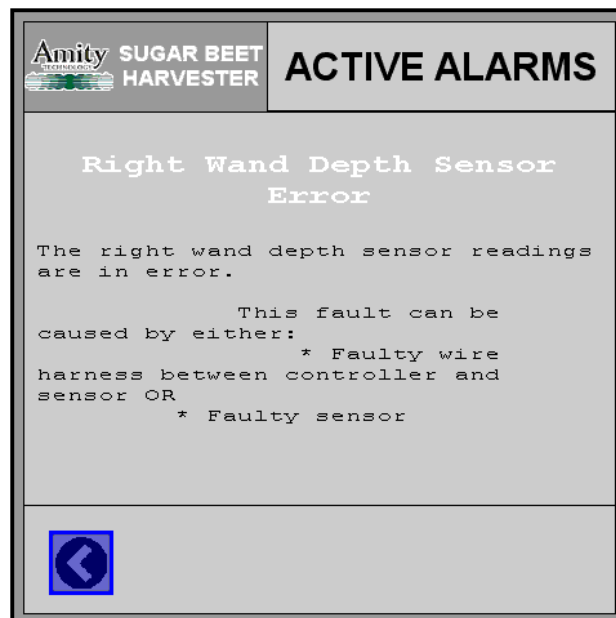


Figure 128—Alarm Information Pop Up

- **D—Scrolling Arrows:** The scrolling arrows allow you to scroll through the alarm list for selection (Figure 124). The alarm highlighted in red is the alarm that will be selected for more information.

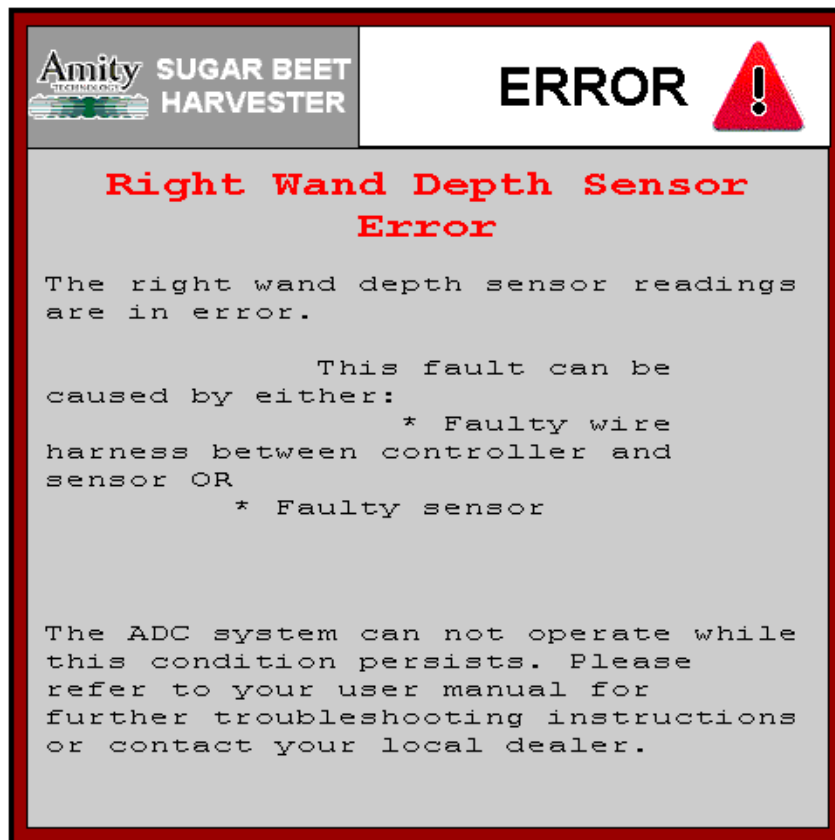


Figure 129—Error Pop Up

When an Alarm is initially caused an Error pop up (Figure 129) will appear and remain until it is acknowledged. Figure 130 is the softkey used to acknowledge the error. The alarm will then be added to the alarm list page. Once the cause of the alarm is addressed the alarm will be removed automatically.



Figure 130—Error Acknowledgement Softkey

13.1.8 Using ADC

Set Up and Calibration:

There are a few things that must be set and one calibration that needs to happen before starting to harvest.

Calibration:

Before harvesting the front wands need to be calibrated so that the system knows where the “zero” depth is. To calibrate the wands, use the hitch to lift the front of the harvester up into the air so that the wands are off the ground and are against their stops. Now using the tractor’s VT find the calibration softkey and select it. Once selected the softkey will change to a green check mark for 3 seconds to signify that the calibration was successful. The calibration is now complete. It is good practice to calibrate the wands every time the system is restarted or if there is ever any wand reading displayed on the main page while the wands are up in the air.

Set Up:

There are a few items that should be set up before harvesting.

Target Depth – Set an initial target depth for how deep you want the lifter wheels to go into the ground. After harvesting for a few yards, stop and measure actual depth the machine is digging and adjust accordingly. This number can be changed while harvesting as well if needed.

Axle Setpoint – Set the height of the rear axles. Typically, this number will be set a 2” in most applications. For muddier conditions or situations that require more cleaning a higher setting will require the beets to climb and therefore slow the beets down while going across the grab rolls.

Joystick Configuration and On/OFF- If you want to use the joystick while harvesting, pick which joystick configuration you want to use from the setting page. The joystick will then have to be enabled before use using the joystick toggle softkey.

Depth Sensitivity- The depth sensitivity is how fast the system will react to depth reading given by the wands. We suggest setting the depth sensitivity on the setting page to 5 to start with and then adjusting to personal preferences or conditions while harvesting to reach a desired machine response.

End Raise On/Off – The end raise function lifts the rear axles all the way up when “END ROW” mode is entered. With the end raise function off the axle will remain in place at the end of each pass.

Use

Once the system is calibrated, set up, and alarm free you are ready to harvest. To harvest follow these steps:

1. Supply constant oil to the valve bank.

2. Turn on the PTO.

a. Once the PTO is on the system status chart will change to a green check mark signifying that the system is ready to enter "AUTO" mode.

3. Drive into the row and engage "AUTO" mode.

a. This can be done in three different ways:

1) Using the tractor's VT select the "AUTO" icon on the main page.

2) Using the tractor's VT selected the "AUTO" softkey.

3) Use the joystick based on which configuration is selected on the setting page.

b. Once "AUTO" mode has been entered the "Current Mode" box will change color to green and say "AUTO" to signify that the system is in "AUTO" mode.

4. Harvest sugar beets.

a. Once "AUTO" mode is engaged the harvester will drop the lifter wheels into the ground and begin to self-level and maintain the target depth.

5. Disengage "AUTO" and lift the machine out of the ground at the end of the row.

a. This can be done in two ways:

1) Disengage "AUTO" in one of the same ways it can be engaged and raise the hitch manually.

2) Engage "END ROW" mode which will disengage "AUTO" and raise the hitch up and out of the ground. "END ROW" can be engaged in the following three ways:

i. Using the tractor's VT selected the "END ROW" softkey.

ii. Using the tractor's VT selected and hold the raise hitch icon for three seconds.

iii. Use the joystick based on which configuration is selected on the setting page.

13.1.9 Alarm Information

The following is a list and descriptions of the possible errors for the system.

Alarm ID Number	Title	Info	Possible Solution
1	Hitch Solenoid Over-current Fault	<p>Too high an output current is detected on the controller output driving the hitch solenoid.</p> <p>Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and solenoid OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage.</p> <p>Replace any damaged parts.</p>
2	Left Axle Solenoid Overcurrent Fault	<p>Too high an output current is detected on the controller output driving the left axle solenoid.</p> <p>Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and solenoid OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage.</p> <p>Replace any damaged parts.</p>
3	Right Axle Solenoid Overcurrent Fault	<p>Too high an output current is detected on the controller output driving the right axle solenoid. Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and solenoid OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage.</p> <p>Replace any damaged parts.</p>
4	Hitch Solenoid Open Fault	<p>Too low an output current is detected on the controller output driving the hitch solenoid.</p> <p>Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and solenoid OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage.</p> <p>Replace any damaged parts.</p>
5	Left Axle Solenoid Open Fault	<p>Too low an output current is detected on the controller output driving the left axle solenoid.</p> <p>Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and solenoid OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage.</p> <p>Replace any damaged parts.</p>
7	Hitch Movement Timeout Fault	<p>Hitch fails to move the a defined distance within the defined time. Fault can be caused by:</p> <ul style="list-style-type: none"> Obstructed hitch OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage.</p> <p>Replace any damaged parts.</p> <p>-Check for any Obstructions</p> <p>-Check for oil pressure or leaks</p>

6	Right Axle Solenoid Open Fault	<p>Too low an output current is detected on the controller output driving the right axle solenoid. Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and solenoid OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage. Replace any damaged parts.</p>
7	Hitch Movement Timeout Fault	<p>Hitch fails to move the a defined distance within the defined time. Fault can be caused by:</p> <ul style="list-style-type: none"> Obstructed hitch OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage. Replace any damaged parts.</p> <p>-Check for any Obstructions</p> <p>-Check for oil pressure or leaks</p>
8	Left Axle Movement Timeout Fault	<p>Left axle fails to move a defined distance within the defined time. Fault can be caused by:</p> <ul style="list-style-type: none"> Obstructed axle OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage. Replace any damaged parts.</p> <p>-Check for any Obstructions</p> <p>-Check for oil pressure or leaks</p>
9	Right Axle Movement Timeout Fault	<p>Right axle fails to move a defined distance within the defined time. Fault can be caused by:</p> <ul style="list-style-type: none"> Obstructed axle OR Faulty solenoid 	<p>-Check wiring harness, harness connectors, and solenoid for damage. Replace any damaged parts.</p> <p>-Check for any Obstructions</p> <p>-Check for oil pressure or leaks</p>
10	Left Wand Depth Sensor Error	<p>Invalid voltage is detected on the left height sensor. Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and sensor Faulty sensor OR Faulty controller 	<p>-Check wiring harness, harness connectors, wand sensor, and controller for damage. Replace any damaged parts.</p>
11	Right Wand Depth Sensor Error	<p>Invalid voltage is detected on the right height sensor. Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and sensor Faulty sensor OR Faulty controller 	<p>-Check wiring harness, harness connectors, wand sensor, and controller for damage. Replace any damaged parts.</p>
12	Left Axle Cylinder Position Sensor Error	<p>Invalid voltage is detected on the left axle cylinder position sensor. Fault can be caused by either:</p> <ul style="list-style-type: none"> Faulty wire harness between controller and sensor Faulty sensor OR Faulty controller 	<p>-Check wiring harness, harness connectors, wand sensor, and controller for damage. Replace any damaged parts.</p>

13	Right Axle Cylinder Position Sensor Error	Invalid voltage is detected on the right axle cylinder position sensor. Fault can be caused by either: <ul style="list-style-type: none"> Faulty wire harness between controller and sensor Faulty sensor OR Faulty controller 	-Check wiring harness, harness connectors, wand sensor, and controller for damage. Replace any damaged parts.
14	Wand Depth Discrepancy Condition	Right and/or left wand depth sensor readings are outside the acceptable target depth range.	-Check wands for mechanical problems or damage -Check for oil flow and leaks
15	Axle Cylinder Setpoint Exceeded Condition	Right and/or left axle cylinder readings are outside the acceptable setpoint range.	-Check for oil flow and leaks
16	Axle Cylinder Position Differential Discrepancy Condition	Difference between right and left axle cylinder readings are outside the acceptable range.	-Check for cylinder damage -Check for oil flow and leaks

13.2 Conversions

1 acre= .404 hectares	1 mph= 1.609 kph
1 acre= 43,560 square feet	1 mile= 1.609 km
1 inch= 2.54 cm	1 psi= 6.895 kPa
1 foot= 0.3048 m	1 GPM= 3.785 LPM
1 lb= .45359 kg	1 hp= .746 kw
1 lb= 16 oz	1 ft-lb= 1.356 N·m

13.3 Trantorque Installation Procedures

Shaft and bore diameters along with surface finishes are critical for the proper installation of a Trantorque bushing. These specifications are held at the factory during manufacturing. If it is necessary to disassemble and reassemble a Trantorque application that is undamaged and intact the following procedures will insure a positive installation. If it is necessary to replace a unit in which the Trantorque or shaft may have come loose, rotated or been damaged, a thorough inspection of the components is necessary to insure the failure will not reoccur.



CAUTION: Do not use lubricants in this installation. The use of any lubricant on the contact surfaces may result in bushing failure and will void all warranties

1. Both the shaft and component bore must be completely free of paint, grease, oil, dirt, and burrs. Clean the surfaces with a non-petroleum based solvent such as isopropyl alcohol.
2. Insert the Trantorque into the bore making sure the mating hub is flush against the shoulder at the hex flats.
3. Insert the shaft fully and hand-tighten the nut until the assembly becomes snug on the shaft.

IMPORTANT: The shaft must fully engage the gripping area of the Trantorque.

4. Using a torque wrench, tighten the nut to the proper torque shown in Table 10.

IMPORTANT: A torque wrench must be used! An impact wrench will not yield the proper torque and the installation will fail. Minimal under-tightening will allow the Trantorque or shaft to spin in the bore.

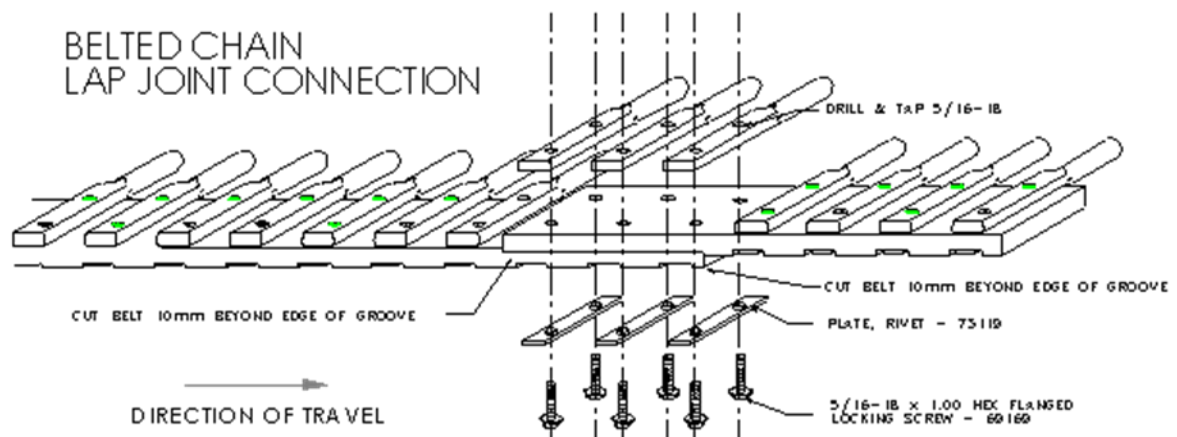
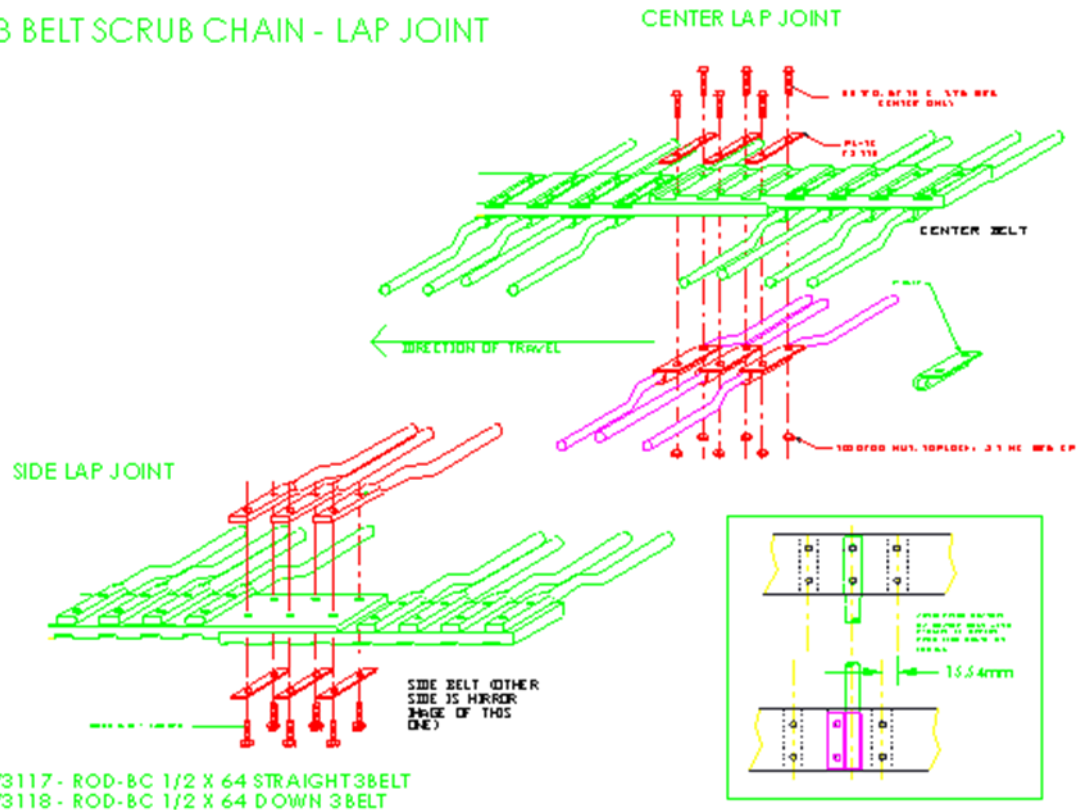
Over-tightening will damage or crack the Trantorque. Do not use an impact wrench during installation.

Table 10: Trantorque Installation Torque

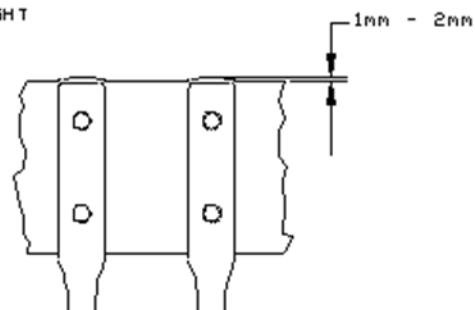
Part #	Description	Torque
58459, 64163	Hub-Trantorque 1.75 in.	270 ft-lb (366 N·m)
58460, 64165	Hub-Trantorque 2.00 in.	470 ft-lb (637 N·m)
59259	Hub-Trantorque 2.25 in.	510 ft-lb, (691 N·m)

13.4 Belted Chain Splice Procedure

3 BELT SCRUB CHAIN - LAP JOINT



WARNING : ENSURE THAT SCREWS ARE SUFFICIENTLY TIGHT TO PRODUCE A BULGE AT THE EDGE OF THE BELT OF BETWEEN 1 AND 2mm (SEE DIAGRAM). FAILURE TO DO SO MAY CAUSE PREMATURE FAILURE AND VOID YOUR WARRANTY



.50 Ø RODS DRILL & TAP .313-18

73122 STRAIGHT - ELEVATOR CHAIN
73123 UP - ELEVATOR CHAIN

73163 STRAIGHT - JUMP CHAIN
73128 UP - JUMP CHAIN

13.5 Tools

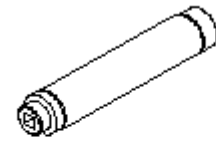
Amity has the following tools available:

Trantorque sockets

(#59107, #59108, #64820)



#64320



#59107 (1 ¾ in., 4.45 cm)

#59108 (2 in., 5.08 cm)

#64820 (2 ¼ in., 5.7 cm)

Trantorque wrench (#64320)

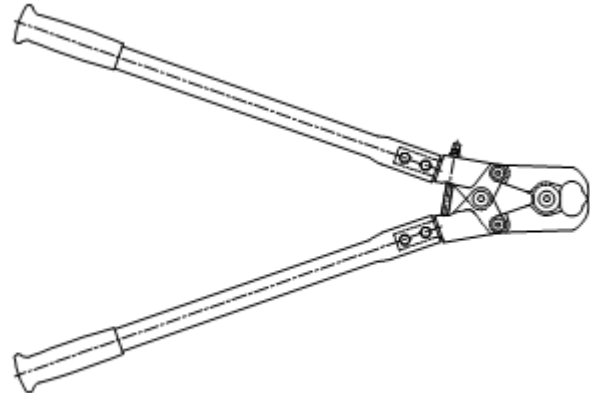
Belted chain link removal to (#62802)



#72417



#72418



#62802

13.6 Tapered Hub/ Sprocket Installation

MST bushings are easy to install and remove. They are split through the barrel and have a taper to provide a true clamp on the shaft. They are keyed to both the hub and the shaft to help during “blind” installations.

Installation:

1. Be sure the tapered cone surfaces of the bushing and the inside of the driven product are clean and free of anti-seize lubricants.
2. Place the bushing in the sprocket or other Martin MST part.
3. Place the cap screws loosely in the “pull up” holes. The bushing remains loose to ensure a sliding fit on the shaft.
4. With the key on the shaft, slide the sprocket to the desired position on shaft. Be sure the heads of the cap screws are accessible.

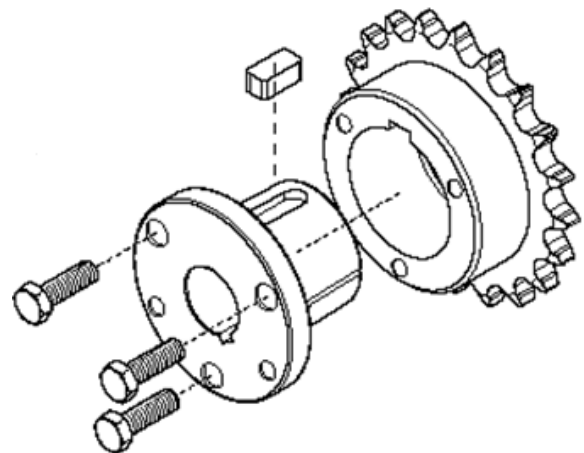


Figure 131: Bushing Installation

- Align the sprocket, and tighten the screws alternately and progressively until they are pulled up tight (see Table 11). Do not use extensions on wrench handles, and do not allow the sprocket to be drawn in contact with the flange of the bushing. There should be a gap between bushing flange and sprocket.



CAUTION: This gap must not be closed.

Table 11: Wrench Torque Values for Tightening Bushings

Removal:

- Loosen and remove the capscrews.
- Insert capscrews in the tapped removal holes.
- Tighten the inserted screws until the sprocket is loose on the shaft.
- Remove the sprocket from the shaft.

MST bushing size	Size of cap screw Inches	Wrench torque in-lbs (N·m)
H	1/4 X 3/4	95 (129)
P	5/16 X 1	192 (260)
Q	3/8 X 1 1/4	348 (472)
R	3/8 X 1 3/4	348 (472)
S	1/2 X 2 1/4	840 (1139)
U	5/8 X 2 3/4	1680 (2278)
W	3/4 X 3	3000 (4068)



WARNING: Use of anti-seize lubricant on tapered cone surfaces or on bolt threads when mounting may result in damage to the sheaves and sprockets. This voids all manufacturers' warranties.



WARNING: Because of the possible danger to person(s) or property from accidents which may result from the improper use of products, it is important that correct procedures be followed: Products must be used in accordance with the engineering information specified in the catalog. Proper installation, maintenance and operation procedures must be observed. The instructions given above must be followed. Inspections should be made as necessary to assure safe operation under prevailing conditions. All rotating power transmission products when used in a drive are potentially dangerous and must be guarded by the user as required by applicable laws, regulations, standards, and good safety practice. (Refer to ANSI Standard B15.1.)

13.7 Torque Wrench Effective Length

To recalculate a torque reading when using a torque adapter, use the following formula, and refer to Figure 98:

$$TW = \frac{TA \cdot L}{L + A}$$

$$L + A$$

TW is the torque setting or dial reading on the wrench.

TA is the torque specification (The actual amount of torque that should be applied to the fastener).

A is the amount that the adapter increases (or reduces) the effective lever length as measured along the centerline of the torque wrench.

L is the lever length of the wrench as measured from the center of the drive to the center of the grip.

The effective length of the torque wrench, measured along the centerline of the torque wrench, is the sum of **L** and **A**.

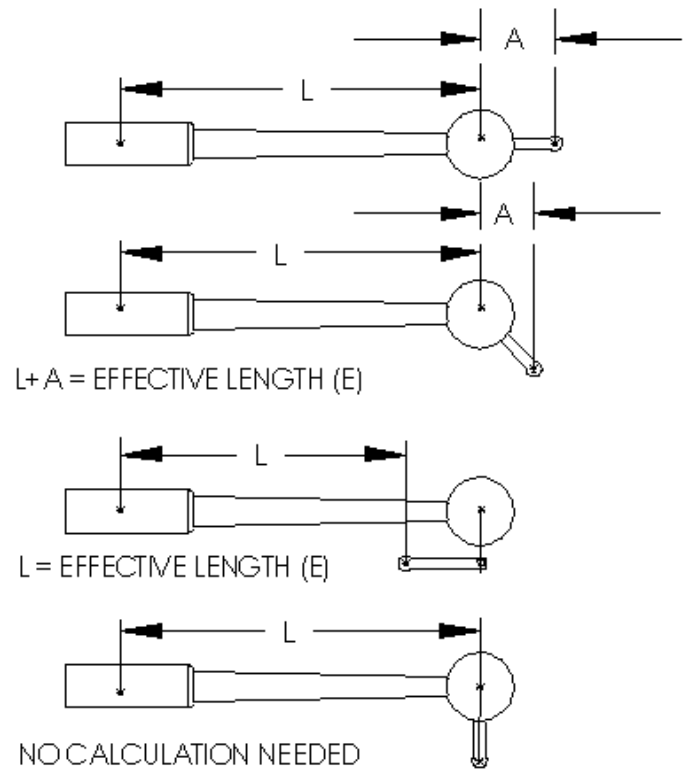


Figure 132: Torque Wrench Effective Length

13.8 Easy Lock Assembly and Removal

Removal:

1. Remove the EASY LOCK[®] tab with a screwdriver (Figure 133).
2. If the guard is chained, remove or hold back the chain to prevent it from blocking the bearing.
3. Turn the bearing in the direction as indicated in (Figure 134). Then, slide guard off the bearing.

Assembly:

1. Align the bearing tabs with the guard bell slots.
2. Slide the bell onto the bearing.
3. Turn the bearing to lock it in place.
4. Snap the EASY LOCK tab into the bell.

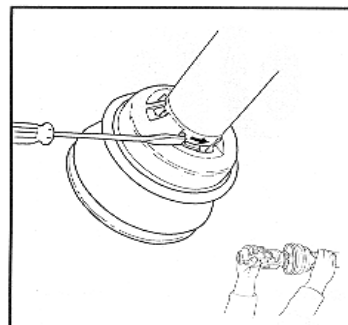


Figure 134: Turning Bearing

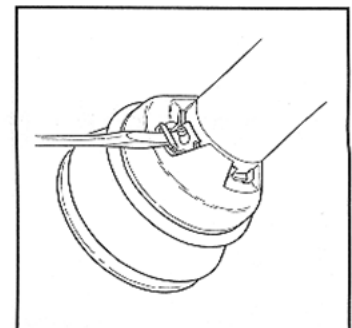


Figure 133: Remove Tab

13.9 Torque Chart

Torque values listed are for coarse thread bolts, in general use only. Do not use these values if a different torque value or tightening procedure is listed for a specific application. Check the tightness of cap screws periodically.

Shear bolts are designed to fail under predetermined loads. Always replace shear bolts with the identical grade.

Fasteners should be replaced with the same or higher grade. If higher grade fasteners are used, they should only be tightened to the strength of the original fastener.

Make sure fastener threads are clean and dry, and thread engagement is properly started. This will prevent them from failing when tightened.

Tighten cap screws with a plastic insert or crimped steel-type lock nuts to approximately 50% of the torque shown in Table 8. Tighten toothed or serrated-type lock nuts to the full torque value.

Table 8: Torque Chart

Size (A)		Grade 5		Grade 8	
Standard	Metric	N*m	lb-ft	N*m	lb-ft
$\frac{1}{4}$ "	.635 cm	12	9	17	12.5
$\frac{5}{16}$ "	.794 cm	25	18	35	26
$\frac{3}{8}$ "	.953 cm	44	33	63	46
$\frac{7}{16}$ "	1.11 cm	70	52	100	75
$\frac{1}{2}$ "	1.27 cm	110	80	150	115
$\frac{9}{16}$ "	1.43 cm	155	115	225	160
$\frac{5}{8}$ "	1.59 cm	215	160	300	225
$\frac{3}{4}$ "	1.91 cm	375	280	550	400
$\frac{7}{8}$ "	2.22 cm	625	450	875	650
1"	2.54 cm	925	675	1300	975
1 $\frac{1}{8}$ "	2.86 cm	1150	850	1850	1350
1 $\frac{1}{4}$ "	3.18 cm	1650	1200	2600	1950
1 $\frac{3}{8}$ "	3.49 cm	2150	1550	3400	2550
1 $\frac{1}{2}$ "	3.81 cm	2850	2100	4550	3350

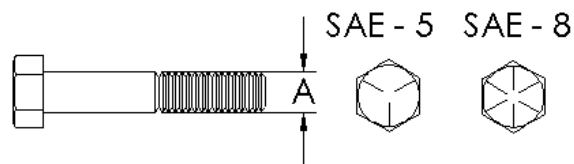


Figure 135: Bolt Grade Identification

